

A Biometric System Based on Single-channel EEG Recording in One-second

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Abstract: In recent years, there are great research interests in using the Electroencephalogram (EEG) signals in biometrics applications. The strength of EEG signals as a biometric comes from its major fraud prevention capability. However, EEG signals are so sensitive, and many factors affect its usage as a biometric; two of these factors are the number of channels, and the required time for acquiring the signal; these factors affect the convenience and practicality. This study proposes a novel approach for EEG-based biometrics that optimizes the channels of acquiring data to only one channel. And the time to only one second. The results are compared against five commonly used classifiers named: KNN, Random Forest (RF), Support Vector Machine (SVM), Decision Tables (DT), and Naïve Bayes (NB). We test the approach on the public Texas data repository. The results prove the constancy of the approach for the eight minutes. The best result of the eyes-closed scenario is Average True Positive Rate (TPR) 99.1% and 98.2% for the eyes-opened. And it reaches 100% for multiple subjects.

Index Terms: Biometrics, Electroencephalogram, Hjorth parameters, K-Nearest Neighbor, Naïve Bayes, Random Forest, and Support Vector Machine.

1. Introduction

Using EEG as a biometric has been suggested in many studies [1], and it has achieved high accuracy results in most of them. EEG as a biometric has several advantages over the conventional biometrics in that EEG is more secure as it is impossible to be imitated or copied for fraud purposes. EEG signals, also, are highly affected by alcohol and drugs so the alcoholic and drug abusers will produce unacceptable signals, and thus, it will be useful in many systems that need a full concentration from the user such as driving, and military work. Moreover, EEG signals are highly affected by stress and mood that makes it difficult to force any person to produce the correct and acceptable signal. EEG signals are suitable for both static and continuous authentication (CA) systems. Furthermore, it can be used only by living subjects. On the other hand, there exist some constraints of the EEG-based biometrics applications, such as mind-reading possibility, other constraints concerning the characteristics of the EEG signals; such as weakness, sensitivity and difficult to be trained.

The main stages of any EEG-based biometrics system are scenarios of capturing the signal, Feature extraction and classification. Scenarios: according to the published studies, many different scenarios of capturing EEG signals have been used in the literature: resting with EC, resting with EO, responding to stimuli [2, 3], performing a set of mental tasks (mental computations [4], imagined speech [5], and imagined movement [6]) where some mental tasks are more appropriate for EEG-based human recognition than others, and involve a particular movement such as moving a single finger [7]. The spatial distribution of the brain activations strongly dependent upon either the person's mental state or the activity performed during the acquisition [8]. For each designed scenario there is an optimal electrode configuration based on the number of channels, their positions, and their density. The less time needed for the human test, the more positive user experience with the system is achieved [9]. Resting scenario provides the most user-friendly scenario as it does not request any instructions to the users only relax. Moreover, it does not require any simulator which reduces the cost as well.

Datasets: despite the EEG-based applications are numerous, but the existence of the public datasets is not sufficient for the biometric researches, and many studies had depended on their private or commercial datasets. Some of the public EEG datasets that can be used in EEG-based biometric studies are the "Australian EEG" database [10], the "CSU EEG" database [11], the "PhysioNet" database [12,13,14,15,16,17], "Deap" database [18], "UCI" database [19], "Texas" data repository [20], "Graz" database [21,22], "ATR" database [23], "Keirn & Aunon" database [24], "BNCI Horizon 2020" database [25].

Features: extracting the appropriate features that are stable and achieve a high accuracy is a fundamental and essential step in the identification model. Many studies used the Autoregressive (AR) model features [26, 27, 28]. Other

studies depended on the statistical features [29]. Recently, authors in [30] extracted features from both spatial and temporal domains of the EEG signals using the spatiotemporal features.

Classification: different classification algorithms were used for EEG recognition systems. Among the most commonly used classifiers are SVM classifier [31, 32, 33], Artificial Neural Network (ANN) [34, 35, 36], and KNN [37, 38, 39, 40]. [37], investigated the robustness of EEG signals to determine its longitudinal stability and effectiveness in user identification systems, and implemented the Discrete Wavelet Transform (DWT) signal decomposition technique to obtain the Alpha-band waves. In particular, they used two statistical features, Root Mean Square, and Integrated EEG. For classification, they also implemented three classification techniques, namely, RF, SVM, and KNN. 10 users were tested in 6 different sessions. They used a decision fusion scheme, applying a majority voting to improve the system performance. Their approach achieved an average accuracy of 80%. In [38], the purpose of their study was to find the best band or the best bands mixture of overt mental stimuli of the EEG signal to identify subjects. They used the DWT to extract features that separate Alpha, Beta and Theta bandwidths of the EEG signal. They tested two different classifiers named ANN, and KNN. Their classification result of the KNN classifier was 50% for the Alpha band, 40% for Beta, and 40% for Theta. C. M. Issac and E. G. M. Kanaga [39] compared classification scores of three classifiers called Weighted KNN, Fine Gaussian SVM, and Linear Discriminant Analysis. The results of their research reported that the Weighted KNN had improved accuracy and precision value compared with the other two classifiers. The accuracy and precision scores of Weighted KNN were 91.7% and 97.09% respectively. In addition to that, the Weighted KNN had less error rate compared to the other two classifiers.

Despite the time needed for testing is a critical factor to create a positive user experience, many researchers have studied the channel reduction while investigating the optimal time for capturing the EEG signals had not been a focal point. In this study, authors have focused on optimizing two important factors that can produce the user's positive or negative experience with the system. These two factors are the number of channels, and the time needed by the user to be recognized.

The rest of this study is organized as follows; Section 2 reviews the closed related work concerning using a single EEG channel. Section 3 illustrates the proposed SCOS approach for person identification using a single EEG channel for just one-second epoch duration. Experimental results are analyzed in section 4. Finally, the conclusion and future work are discussed in section 5.

2. Related Work

Most of the previous studies in EEG biometric have utilized multi-channel data. As single-channel EEG devices have become widely available, this encouraged researchers to do more studies in using the single-channel approach. With a relaxed EC scenario, 13 subjects were employed for testing the approach in [26]. Comparing the results of three different classifiers named ANN, SVM, and LDA. Their best-achieved result was 87% using the AR model with the SVM classifier. Comparing to our approach, Zhu Dan et al. [26] have utilized a recording of 6-minutes for each subject concentrating on only one factor which is the number of channels.

J. Chuang et al. [41] studied the usability of different scenarios naming breathing, finger, sport, song, audio, color and pass. They found that subjects have different orientations of the tasks based on the difficulty and enjoy the tasks. Although their results had achieved 99%, the size of their dataset was only 15 subjects. Comparing to our approach their experiments need the user to follow some instructions and perform specific tasks. While the experiments in our approach need only relaxation. Also their approach needed 5 seconds recording.

While, M. T. Curran et al. [42] used the low-cost Neurosky Mindwave Mobile wireless EEG headset, tested 12 participants who performed five mental tasks naming breath, song, face, listen and cube. The study had indicated that ear-EEG showed ability as a practical authentication method science it is integrated into earbuds. Comparing to our approach, [42] needs 12 seconds recording of performing specific tasks.

Furthermore, R. Suppiah and A. P. Vinod [9] studied using EEG data during both closed and open resting scenarios, investigating the optimal period needed for identification and verification purposes. They achieved results in the range of 97% and99%; the best of their results were acquired using 10-seconds epochs. The proposed approach achieved a high accuracy result on a large dataset (to some extent), but their study didn't measure the effect of time on the stability of the achieved results.

More recently, E. S. Haukipuro et al. [7] explored the effectiveness of three different EEG authentication scenarios, which are resting, thinking about an image and moving one finger. They extracted features from Mel-Frequency Cepstral Coefficients (MFCC), and frequency power spectrum utilizing a multilayer perceptron classifier. Results for their research indicated that EEG data from different tasks contain sufficient information that distinguishes among users and hence proper for identification purposes across tasks (to some extent), and vice versa. But the result was 76% for 27 subjects.

The previously discussed single-channel studies except for study [9] depended on private small datasets and this is because of the rareness of the public large datasets which are appropriate for the EEG-biometrics studies.

3. Proposed Approach

In this section, a novel approach for EEG-based human recognition is presented. This approach optimizes two important factors of EEG-based biometric systems which are (i) length of recording the EEG signals, (ii) number of channels.

3.1. Preprocessing

This approach uses all power in EEG signals and therefore all of information that is linked to cognitive brain functions and psychological states: Delta, Theta, Alpha, Beta and Gamma.

For each subject, the data of the Iz channel [9] is extracted, and then these data are segmented to 1-sec epochs excluding the first and last epoch of each minute, each minute of data are broken up into 58 epochs of one-second each.

3.2. Features extraction

Although the HjP have been used in many studies for the EEG-classification studies such as human emotion recognition [43, 44], effect of emotional assessment [45] and classification of seizure and seizure free [46, 47]. According to our knowledge, no studies exist utilizing these parameters in EEG-based biometrics. The HjP (Activity, Mobility and Complexity) are quantitative techniques for the EEG trace in the time and frequency domains.

- *i.* Activity is measured by the means of the amplitude variance, which has the required additive characteristic that allows the integration of various measurements during epoch to only one figure.
- *ii. Mobility* represents the relative average slope and it is computed by computing the square root of the ratio of first derivative variances to the amplitude.
- *iii.* Complexity is defined as the ratio of first derivative mobility to mobility.

The parameters can be determined using the following equations:

$$Activity = \sigma^2 \tag{1}$$

$$Mobility = \sqrt{\frac{\sigma_d^2}{\sigma_x^2}} = \frac{\sigma_d}{\sigma_x}$$
(2)

$$Complexity = \sqrt{\frac{\frac{\sigma_{dd}^2}{\sigma_d^2}}{\frac{\sigma_d^2}{\sigma_x^2}} = \frac{\frac{\sigma_{dd}}{\sigma_d}}{\frac{\sigma_d}{\sigma_x}}}$$
(3)

A fusion of the computed 3-HjP and the extracted values of the signal has been applied for each epoch.

3.3. Classification

The KNN classifier is used. KNN is a supervised-instance based learning algorithm. The basic concept of the K-NN algorithm is to measure the distance between the training and testing features. When the nearest distance of the training samples has been found, its class will be predicted for the test class. The distance between two points, is calculated according to the formula [48]:

$$Distance(X_1, X_2) = \sqrt{\sum_{i=1}^{n} (X_{1i} - X_{2i})^2}$$
(4)

Where $X_{1i} = (X_{11}, X_{12}, \dots, X_{1n})$ and $X_{2i} = (X_{21}, X_{22}, \dots, X_{2n})$

4. Experimental Results

This study has used the public Texas data repository [20] that contains data of 22 subjects (denoted as s1-s22), 72 EEG Channels for a resting scenario, four minutes for eye opened and four minutes for eye closed (recording one minute with eyes opened and the next with eye closed). So, in this study, the authors have used minutes 2, 4, 6 and 8 for eyes-closed scenario and minutes 1, 3, 5 and 7 for eyes-opened scenario. Only 21 subjects who recorded 4 minutes of resting EC have been used, while the subject number 6 only has 2 minutes with eyes closed, so the authors have excluded him/her from this study.

In this study, the authors used the Waikato Environment for Knowledge Analysis 3.8.3 tool (WEKA 3.8.3) [49]. And the EEG signals were preprocessed using the Matlab EEGlab-toolbox [50]. Extracting data of the Iz channel, and

then the signals were segmented to 1-sec epochs, excluding the first and last epoch of each minute; the result is 4872 instances for the 21 subjects for each scenario, and 1218 instances for each minute. Figure 1 shows a sample of the extracted epochs.



Fig.1. EEG print of channel Iz for one-second epoch

(a) Subject 3 epoch 1 eyes-opened, (b) Subject 21 epoch 1 eyes-opened, (c) Subject 3 epoch 1 eyes-closed, (d) Subject 21 epoch 1 eyes-closed

After that, a fusion of the three HjP with the 256-extracted samples for each epoch is applied. All the data were shuffled, then it was divided using a ten-fold cross-validation method, this method can guarantee unbiased performance measures.

To validate the performance of the proposed approach, we conducted four experiments: In experiment 1, classifiers were employed to the eyes-closed scenario without applying features fusion. In experiment 2, the authors employed the classification techniques to the eyes-closed after applying features fusion method. While in experiment 3, the eyes-opened scenario without applying the features fusion has executed. And finally, in experiment 4 the features fusion on the eyes-opened scenario has done.

The experiments are measured using five evaluators named, True Positive Rate (TPR), False Positive Rate (FPR), Precision, Recall and F-measure [51].

$$TPR = TP/(TP + FN) \tag{5}$$

$$FPR = FP/(FP + TN) \tag{6}$$

$$Precision = \text{Confidence} = TP/(TP + FP)$$
(7)

$$Recall = Sensitivity = TPR = TP/(TP + FN)$$
(8)

$$F_{measure} = 2 * Precision * Recall/(Precision + Recall)$$
(9)

Where TP is True Positive, FN is False Negative, FP is False Positive and TN is True Negative.

4.1. Experiment 1

In the first experiment, we applied the proposed approach on the eyes-closed scenario without applying the fusion of the features. And we performed a comparison among the five tested classifiers as shown in figure 1.

As can be noticed, the results of RF classifier are the best and the most stable among the tested classifiers, which are; 91%, 94.3%, 95.2%, 95.5% for the four minutes respectively. But these results need more improvements to be applicable.



Fig.2. Classifiers performance for each minute without features fusion

4.2. Experiment 2

This experiment has been performed exactly as experiment1, but to improve the results, the authors proposed a features fusion level between the extracted samples of the EEG signal and the calculated HjP.

The best results are achieved using the KNN classifier as shown in table 1 and the results for the four minutes are 93.4%, 98.7%, 99.1% and 96% respectively.

Table 1.classifiers performance in experiment 2

			With featu	res-fusion	
		Min2	Min4	Min6	Min8
	TPR	0.873	0.946	0.952	0.955
	FPR	0.006	0.003	0.002	0.002
DT	Precision	0.885	0.950	0.952	0.957
	Recall	0.873	0.946	0.952	0.955
	F-measure	0.871	0.945	0.951	0.949
	TPR	0.883	0.924	0.907	0.907
	FPR	0.006	0.004	0.005	0.005
SVM	Precision	0.903	0.931	0.914	0.912
	Recall	0.883	0.924	0.907	0.907
	F-measure	0.882	0.921	0.906	0.905
	TPR	0.874	0.928	0.954	0.944
	FPR	0.006	0.004	0.002	0.003
NB	Precision	0.883	0.928	0.959	0.936
	Recall	0.874	0.928	0954	0.944
	F-measure	0.871	0.926	0953	0.936
	TP	0.918	0.950	0.954	0.959
	FP	0.004	0.003	0.002	0.002
RF	Precision	0.920	0.950	0.955	0.957
	Recall	0.918	0.950	0.954	0.959
	F-measure	0.917	0.950	0.953	0.957
	TPR	0.934	0.987	0.991	0.960
	FPR	0.003	0.001	0.000	0.002
KNN	Precision	0.935	0.987	0.991	0.960
	Recall	0.934	0.987	0.991	0.960
	F-measure	0.934	0.987	0.991	0.959

The results show that the features fusion has achieved a considerable improvement to the performance of all the tested classifiers, for example, the accuracy of SVM at minute 2 is 78% without the features fusion while after the features level fusion, the results have achieved 88.3% and also the improvement for all the tested classifiers with different rates of improvement.



Fig.3. Classifiers performance for each minute with features fusion

The comparison between the performance of the KNN classifier in the experiment1 and the experiment2 in figure 4 shows a significant improvement achieved in the experiment2; as the features-fusion improved the results of the KNN classifier for the four minutes with 4%, 3.7%, 5.4% and 0.6% respectively.



Fig.4. The effect of features fusion on the KNN classifier

Tables 2,3,4,5 show the confusion matrices by the class of the proposed approach at minutes 2, 4, 6, 8. These matrices show that many subjects have been recognized with an accuracy of 100% (such as subjects: f, n, p, s and u) where the proposed approach has correctly recognized all the 58 epochs of them through the four minutes.

Table 2. The confusion matrix at min	2
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	Cor	nfus	sion	n M	atr:	ix :																	
a	b	с	d	e	f	g	h	i	Ĵ	k	1	m	n	0	P	q	r	s	t	u		< 0	lassified as
56	0	0	0	2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	a =	1
0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	b =	10
0	0	49	0	0	0	5	0	4	0	0	0	0	0	0	0	0	0	0	0	0	1	c =	11
0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	d =	12
2	0	0	0	56	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	e =	13
0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	f =	14
0	0	6	0	0	0	39	0	13	0	0	0	0	0	0	0	0	0	0	0	0	1	g =	15
0	0	0	0	0	0	0	57	0	0	0	0	0	0	0	0	0	0	0	1	0	1	h =	16
0	0	6	0	0	0	12	0	38	0	2	0	0	0	0	0	0	0	0	0	0	1	i =	17
0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	1	j =	18
0	0	0	0	0	0	0	0	1	0	57	0	0	0	0	0	0	0	0	0	0	1	k =	19
0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	1	1 =	2
0	0	0	0	0	0	0	0	0	0	0	7	51	0	0	0	0	0	0	0	0	1	m =	3
0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	1	n =	4
0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	1	o =	5
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	1	p =	7
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	47	11	0	0	0	1	q =	8
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	7	51	0	0	0	1	r =	9
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	1	s =	20
0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	57	0	1	t =	21
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	1	u =	22

Table 3. The confusion matrix at min 4

	Cor	nfu	sio	n M	atr	ix =																			
a	b	с	d	e	f	g	h	i	j	k	1	m	n	0	p	q	r	s	τ	u		<	- (classified	as
58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	a	=	1	
0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	b	=	10	
0	0	52	0	0	0	6	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	C	=	11	
0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	d	=	12	
0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	e	=	13	
0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	f	=	14	
0	0	8	0	0	0	49	0	0	0	0	1	0	0	0	0	0	0	0	0	0	1	g	=	15	
0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	1	h	=	16	
0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	1	i	=	17	
0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	1	Ĵ	=	18	
0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	1	k	=	19	
0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	1	1	=	2	
0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	1	m	=	3	
0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	1	n	=	4	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	1	0	=	5	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	1	p	=	7	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	1	q	=	8	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	57	0	0	0	1	r	=	9	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	1	S	=	20	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	1	t	=	21	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	1	u	=	22	

Table 4.The confusion matrix at min 6

=== Confusion Matrix ===

a	b	C	d	e	f	g	h	i	Ĵ	k	1	m	n	0	p	q	r	S	t	u		< (classified	as
58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	a =	1	
0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	b =	10	
0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	c =	11	
0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	d =	12	
0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	e =	13	
0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	f =	14	
0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	g =	15	
0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	1	h =	16	
0	0	0	0	0	0	0	0	57	0	1	0	0	0	0	0	0	0	0	0	0	1	i =	17	
0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	1	j =	18	
0	0	0	0	0	0	0	0	1	0	57	0	0	0	0	0	0	0	0	0	0	1	k =	19	
0	0	1	0	0	0	1	0	0	0	0	56	0	0	0	0	0	0	0	0	0	1	1 =	2	
0	0	0	0	0	0	0	0	0	0	0	0	57	0	0	0	0	0	0	0	1	1	m =	3	
0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	1	n =	4	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	56	0	0	0	0	2	0	1	0 =	5	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	1	p =	7	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	1	q =	8	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	T	r =	9	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	1	s =	20	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	4	0	0	0	0	54	0	1	t =	21	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	1	u =	22	

Table 5. The confusion matrix at min 8

=== Confusion Matrix ===

a	b	c	d	e	f	g	h	i	j	k	1	m	n	0	p	q	r	s	t	u		<	classified as
58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	a =	= 1
0	52	0	0	0	0	0	0	0	0	0	0	0	0	0	0	4	2	0	0	0	Ĩ	b =	= 10
0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	U.	c =	= 11
0	0	0	57	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	d =	= 12
0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	e =	= 13
0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	f :	= 14
0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	g =	= 15
0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	1	h =	= 16
0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	1	i =	= 17
0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	ĩ	j -	= 18
0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	1	k =	= 19
0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	1	1 -	= 2
0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	1	m =	= 3
0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	1	n =	= 4
0	0	0	0	0	0	0	0	0	0	0	0	0	0	57	0	0	0	0	1	0	1	0 =	= 5
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	1	p =	= 7
0	11	0	0	0	0	0	0	0	0	0	0	0	0	0	0	39	8	0	0	0	1	q =	= 8
0	2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	18	38	0	0	0	Ĩ	r -	= 9
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	Т	S =	= 20
0	0	0	0	0	0	0	0	0	0	0	0	0	0	2	0	0	0	0	56	0	1	t :	= 21
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	1	u =	= 22

4.3. Experiment 3

In this experiment, we applied the proposed approach on the eyes-opened scenario without applying the fusion of the features. And we performed a comparison among the five tested classifiers as shown in figure 5. As can be noticed, the results of RF classifier are the best and the most stable among the tested classifiers, which are; 92.5%, 93.8%, 93.5%, 91.8% for the four minutes respectively. But these results also need more improvements to be applicable.



Fig.5. Classifiers performance for each minute without features fusion

4.4. Experiment 4

To improve the previous results, the authors proposed a features fusion level between the extracted samples of the EEG signal and the calculated HjP. The best results are achieved using the KNN classifier as shown in table 6 and the results for the four minutes are 96.8%, 98.2%, 97.7% and 96.6% respectively.

Table 6. Classifiers performance in experiment 4

			With featu	res-fusion	
		Min 1	Min 3	Min 5	Min 7
	TPR	0.937	0.976	0.948	0.942
	FPR	0.003	0.001	0.003	0.003
DT	Precision	0.941	0.980	0.948	0.943
	Recall	0.937	0.976	0.948	0.942
	F-measure	0.936	0.975	0.948	0.941
	TPR	0.929	0.921	0.872	0.851
	FPR	0.004	0.004	0.006	0.007
SVM	Precision	0.933	0.928	0.886	0.856
	Recall	0.929	0.921	0.872	0.851
	F-measure	0.929	0.920	0.867	0.843
	TPR	0.945	0.979	0.955	0.937
	FPR	0.003	0.001	0.002	0.003
NB	Precision	0.948	0.980	0.958	0.939
	Recall	0.945	0.979	0.955	0.937
	F-measure	0.945	0.978	0.955	0.936
	TPR	0.957	0.981	0.968	0.957
	FPR	0.002	0.001	0.002	0.002
RF	Precision	0.960	0.984	0.969	0.958
	Recall	0.957	0.981	0.968	0.957
	F-measure	0.957	0.981	0.968	0.957
	TPR	0.968	0982	0.977	0.966
	FPR	0.002	0.001	0.001	0.002
KNN	Precision	0.968	0.983	0.977	0.967
	Recall	0.968	0.982	0.977	0.966
	F-measure	0.968	0.982	0.977	0.966

The comparison between results in figure 5 and results in figure 6 show that the features fusion has achieved a considerable improvement to the performance of all the tested classifiers.



Fig.6. Classifiers performance for each minute with features fusion

And the comparison between the performance of the KNN classifier in experiment 3 and experiment4 in figure 7 shows a significant improvement achieved in experiment 4; as the features-fusion improved the results of the KNN classifier for the four minutes with 3.3%, 3.4%, 3.6% and 4.2% respectively.



Fig.7. The effect of features fusion on the KNN classifier

Tables 7, 8, 9, 10 show the confusion matrices by the class of the proposed approach at minutes 1, 3, 5, 7. These matrices show that many subjects have been identified with an accuracy of 100%. Such as subjects: e, i, j, n, p and s.

Table 7. The confusion matrix at min 1

	Cor	nfus	sion	n Ma	atr:	ix =																
а	b	С	d	e	f	g	h	i	j	k	1	m	n	0	р	q	r	s	t	u		< classified as
58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	a = 1
0	57	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	1	b = 10
0	0	46	0	0	0	12	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	c = 11
0	0	0	57	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	1	d = 12
0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	e = 13
0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	f = 14
0	0	11	0	0	0	47	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	g = 15
0	0	0	0	0	0	0	54	0	0	0	0	0	0	2	0	0	0	0	2	0	1	h = 16
0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	1	i = 17
0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	1	j = 18
0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	1	k = 19
0	0	0	0	0	0	0	0	0	0	0	57	0	0	0	0	0	0	0	0	1	1	1 = 2
0	0	0	0	0	0	0	0	0	0	0	0	56	0	0	0	0	0	0	0	0	1	m = 3
0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	1	n = 4
0	0	0	0	0	0	0	1	0	0	0	0	0	0	57	0	0	0	0	0	0	1	0 = 5
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	i.	p = 7
0	4	0	0	0	0	0	0	0	0	0	0	0	0	0	0	54	0	0	0	0	i.	g = 8
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	i.	r = 9
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	÷	s = 20
0	0	0	1	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	56	0	÷	t = 21
0	0	0	0	0	0	0	0	0	0	0	2	0	0	0	0	0	0	0	0	56	÷	u = 22
											-											

Table 8. The confusion matrix at min 3

	Cor	ifus	sion	n M	atr:	ix :																
a	b	с	d	e	f	g	h	i	j	k	1	m	n	0	р	q	r	s	t	u		< classified as
58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	a = 1
0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	b = 10
0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	c = 11
0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	d = 12
0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	e = 13
0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	f = 14
0	0	1	0	0	0	57	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	g = 15
0	0	0	0	0	0	0	55	0	0	0	0	0	0	0	0	0	0	0	3	0	Т	h = 16
0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	Т	i = 17
0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	Т	j = 18
0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	Т	k = 19
0	0	0	0	0	0	0	0	0	0	0	57	0	0	0	0	0	0	0	0	0	Т	1 = 2
0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	1	m = 3
0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	1	n = 4
0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	1	0 = 5
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	Т	p = 7
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	56	2	0	0	0	Т	q = 8
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	57	0	0	0	1	r = 9
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	1	s = 20
0	0	0	0	0	0	0	15	0	0	0	0	0	0	0	0	0	0	0	43	0	1	t = 21
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	i.	u = 22

Table 9. The confusion matrix at min 5

=== Confusion Matrix ===

a	b	С	d	e	f	g	h	i	j	k	1	m	n	0	р	q	r	s	t	u		< classified as
58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	a = 1
0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	b = 10
0	0	46	0	0	0	11	0	0	0	0	1	0	0	0	0	0	0	0	0	0	I.	c = 11
0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	d = 12
0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	e = 13
0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	f = 14
0	0	8	0	0	0	50	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	g = 15
0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	I.	h = 16
0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	1	i = 17
0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	1	j = 18
0	0	0	0	0	0	0	0	1	0	57	0	0	0	0	0	0	0	0	0	0	1	k = 19
0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	1	1 = 2
0	0	0	0	0	0	0	0	0	0	0	0	56	0	0	0	0	0	0	0	2	1	m = 3
0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	1	n = 4
0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	1	o = 5
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	1	p = 7
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	1	q = 8
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	1	r = 9
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	1	s = 20
0	0	0	0	0	0	0	1	0	0	0	0	0	0	2	0	0	0	0	55	0	1	t = 21
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	1	u = 22

Table 10. The confusion matrix at min 7

=== Confusion Matrix ===

а	b	С	d	e	f	g	h	i	Ĵ	k	1	m	n	0	p	q	r	s	t	u		< classified as
57	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	a = 1
0	55	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	3	0	0	0	1	b = 10
0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Т	c = 11
0	0	0	55	0	1	0	2	0	0	0	0	0	0	0	0	0	0	0	0	0	1	d = 12
0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	Т	e = 13
0	0	0	3	0	50	0	5	0	0	0	0	0	0	0	0	0	0	0	0	0	1	f = 14
0	0	0	0	0	0	57	0	0	0	0	1	0	0	0	0	0	0	0	0	0	1	g = 15
0	0	0	4	0	6	0	48	0	0	0	0	0	0	0	0	0	0	0	0	0	1	h = 16
0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	0	Т	i = 17
0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	0	Т	j = 18
0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	0	1	k = 19
0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	0	1	1 = 2
0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	0	Т	m = 3
0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	0	0	1	n = 4
0	0	0	0	0	0	0	0	0	0	0	0	0	0	57	0	0	0	0	1	0	1	o = 5
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	0	0	0	1	p = 7
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	52	6	0	0	0	1	q = 8
0	2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	2	54	0	0	0	Т	r = 9
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	0	0	Т	s = 20
0	0	0	0	0	0	0	0	0	0	0	0	0	0	5	0	0	0	0	53	0	Т	t = 21
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	58	I.	u = 22

5. Conclusions and Future Work

This study has focused on developing a new approach to human recognition utilizing EEG signals. The main contribution of this study is optimizing the time needed for capturing the signal to one-second only, extracted using only single-channel. The uniqueness of our proposed method relies on the features-fusion level between the signal and the Hjorth parameters. We emphasized the proposed technique by testing on a public dataset in the two different states of resting. We conducted a comparison among five different classifiers' performance without and with using the proposed technique and the results show the improvement in the performance of all the tested classifiers. The results proved the proposed approach constancy for all the subjects, achieving TPR of 100% for multiple subjects and average True Positive Rate (TPR) 99.1% for eyes-closed scenario and 98.2% for eyes-opened scenario. In the future, large datasets will be tested and also data acquired from the wearable EEG devices.

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