A Dynamic Object Identification Protocol for Intelligent Robotic Systems

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Abstract—Robotics has enabled the lessening of human intervention in most of the mission critical applications. For this to happen, the foremost requirement is the identification of objects and their classification. This study aims at building a humanoid robot capable of identifying objects based on the characters on their labels. Traditionally this is facilitated by the analysis of correlation value. However, only relying on this parameter is highly error-prone. This study enhances the efficiency of object identification by using image segmentation and thresholding methods. We have introduced a pre-processing stage for images while subjecting them to correlation coefficient test. It was found that the proposed method gave better recognition rates when compared to the conventional way of testing an image for correlation with another. The obtained results were statistically analysed using the ANOVA test suite. The correlation values with respect to the characters where then fed to the robot to uniquely identify a given image, pick the object using its arm and then place the object in the appropriate container.

Index Terms—Robotics, image segmentation, correlation coefficient, optical character recognition, object recognition.

I. INTRODUCTION

Currently human computer interaction has been researched to ease the process of human intervention in computing and various other day to day tasks though applications like natural language processing, brain-computer interface [1, 2], speech recognition, etc. Another domain which also aims to achieve the same goal is robotics. Robotics has tremendous applications in present era. Currently robotic surgeries are found to be more accurate and precise in nature when compared to the traditional invasive surgeries [3].

Character recognition is an important aspect of pattern recognition which has wide spread use these days. The characters under consideration determine the complexity of the character recognition problem. The classification and identification of optical patterns in a digital image is termed as optical character recognition (OCR). The characters are basically alphanumeric or any other characters in a given language. The technique comprises of phases like segmentation, feature extraction and classification. It finds tremendous applications in an assortment of applications like document or signature verification in original papers, data source, invoices, passport documents, receipts, bank statement, mail; text-to-speech translation, etc.

An important step in character recognition from images is image segmentation. It deals with partitioning a given image into multiple segments. It is used to modify or simplify the representation of images that renders effective analysis at decreased intricacy. In [4], a method to detect the vehicle’s number plate at night is developed using Iterative Threshold Segmentation algorithm. A well-known technique used for image thresholding is the Otsu’s method [5]. In our implementation, we have introduced a preprocessing stage for images of characters before subjecting them to correlation coefficient test with the aid of image thresholding and segmentation. We then assess the correlation coefficient in two ways-by preprocessing them using our method and without any preprocessing.

The rest of the paper is organized as follows. Section II deals with the related work pertaining to the study. The implementation of the overall system is discussed in Section III. The results obtained are given in Section IV which are statistically analysed. The paper concludes in Section V.

II. RELATED WORK

OCR technology has been deployed to process historical documents [6]. OCR is used especially in domains like computer vision, artificial intelligence and pattern recognition. Many classifiers have been studied exclusively to recognize handwritten characters [7]. Artificial neural networks have been considered to be a powerful classifier due to their high computation rate achieved by massive parallelism [8, 9]. Hindi characters have been recognized as in [10].

A. Correlation Coefficient

Correlation Coefficient is a method of assessing the amount of linear relationship that exists between two quantities under test, designed by Karl Pearson in 1895. The Pearson’s correlation coefficient is given by [11]:

\[ r = \frac{\sum_{i=1}^{n}(x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^{n}(x_i - \bar{x})^2 \sum_{i=1}^{n}(y_i - \bar{y})^2}} \]

where \( x_i \) and \( y_i \) are the individual sample points indexed with \( i \), \( n \) is the number of samples, and \( \bar{x}, \bar{y} \) are the mean values of \( x \) and \( y \) respectively.
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\[ r = \frac{\sum (x_i - x_m)(y_i - y_m)}{\sqrt{\sum (x_i - x_m)^2 \sum (y_i - y_m)^2}} \]  

where \( x_m \) and \( y_m \) represents the mean of intensity values of the 1st and 2nd image respectively; \( x_i \) and \( y_i \) corresponds to the values of the intensities of the \( i \)th pixel in 1st and 2nd images respectively. If the two images are absolutely identical, then the value of the correlation coefficient is 1, the value of \( r = -1 \), the two images are said to be anti-correlated. A value of zero indicates that the two images are absolutely uncorrelated \[12\]. In \[13\], the impact of correlation coefficient is studied with respect to face recognition.

The correlation coefficient is vulnerable to the pincushioning, image skewing, and vignetting that is inevitable in imaging systems \[14\]. Pincushioning means that the edges of the image are concave. Image skewing occurs when an image slants in one direction. Vignetting is a reduction in the image intensity near the edges due to optical light collecting considerations. Such distortions are particularly prevalent in scanning electron microscope pictures \[15\] due to the complexities and non-linearities of electron optics. In practice, minor deviations in the object’s position relative to the camera, distortions in the pixel noise, imaging system; and other factors produce an \( r \) value less than 1, even if the object has not been moved or physically altered in any manner \[15\].

The aim of our implementation is to do away with the shortcomings associated with correlation coefficient like distortions in the imaging system and slight, pixel noise, deviations in the positioning of the object with respect to the camera. Hence we introduce steps wherein the image is prepared to undergo the correlation coefficient test and bestow proper results even in unconstrained environments. This technique of assessing the correlation was also compared with the conventional means of obtaining correlation coefficient, wherein the images are compared with proper preprocessing.

![Fig. 1 PCB design](image1.png)

**III. IMPLEMENTATION**

**A. Hardware and Software requirements**

The IC chips used for the implementation consisted of Atmega-8L, Voltage controller 7805, L293D, HT12D and HT12E. The motors used for the locomotion of the robot composed of geared DC motor-5-10 rpm and DC motor of 30 rpm. The camera used for image acquisition was Samsung Galaxy S3 smart phone front camera of 1.9 mega pixels. The power supply was rendered using 9V battery and SMPS based adapter of output specifications-9V, 2A. Other components like resistors of 1-10k, IN 4007 p-n junction diode, 1-10 micro farad capacitors and LEDs were used. The schematic representation of the PCB design is as shown in Fig. 1, developed using PBC Wizard Professional edition \[16\].

![Fig. 2 Entire system design schema](image2.png)

Fig. 2 shows the schematic representation of the overall system design. Camera is connected to the computer system. This connection can be rendered in a wireless mode or by using a wired cable. In our implementation, we have connected a phone camera with the computer system using Bluetooth. After successful initialization of the camera, the image acquisition phase starts. These images are recognized using the proposed method and the signal is transmitted using RF transmitter receiver to the microcontroller (ATMEGA 8L) in a wireless mode. Accordingly, the microcontroller gives
the output to L293D which in turn drives the motor. Motor drives the arm and place the block in their respective position. A success message is displayed for correct object placement in the right container. Fig. 3 shows the setup of the robotic system.

B. Methodology

The core of the working of the robot was the recognition of characters labelled on the objects. The pseudo code of the technique deployed is as follows:

1. Image acquisition from real time feed.
2. Image thresholding using Otsu's method.
3. Recognizing the number of characters in the image.
4. De-noising the image by eliminating the unwanted pixel areas.
5. Segmentation of the image and extraction of characters.
6. Assessment of correlation coefficient of the image with the images in the database.

For( number of images in the database) {
    Correlation_coefficient(processed image, database image)
    If maximum (Correlation_coefficient) {
        Character match
        Return this image
    }
}

C. Image analysis

This section explains the analysis of the image acquired via camera. The image consisted of English alphabets and numbers in 5 different font styles in the following order:

1) Arial Black
2) Times New Roman
3) Calibri
4) Book Antiqua
5) Bookman Old Style

Fig. 4 shows the image of letter “A” taken in the above 5 font styles (with white background) for analysis. To further test the accuracy of our method, we acquired the image of a character with 3 different light intensities (see Fig. 5). The naming convention followed for each image in this case is- S FONTSTYLE NUMBER _IMAGENUMBER. The letter “S” in the naming convention denotes ‘shades’ so as to distinguish these datasets from the ones in Fig.4.
IV. RESULTS AND DISCUSSIONS

A. Case 1: Analysis of images with five different font styles

Fig. 6 shows the results obtained for images of five different font styles. X axis depicts the five font styles with notations A1 through A5. The ordering of these font styles is the same as mentioned in Section III.C. The correlation coefficient values obtained are plotted along Y axis. Along the X-axis, each font style is compared with the rest of the five font styles for their respective correlation coefficient values and the same are plotted. This is calculated using two methods: traditional and the proposed method. The blue bars represent the conventional method of comparison while the red bars indicate the results obtained using the proposed scheme. The red bars are comparatively higher than the blue bars which is indicative of the fact that the proposed method outperformed the conventional method of comparison of images of characters.

Single factor ANOVA for case 1

The results shown in Fig. 6 are tested statistically using single factor ANOVA suite with the following hypothesis:

H₀: All the images (with different font styles) return same results.
H₁: All the images (with different font styles) do not return same results.

Table 1 shows the summary of statistical results. Since the p-value returned by ANOVA test (Table 2) is less than 0.05, we reject the null hypothesis. Hence, the means of the correlation coefficients aren’t equal. Hence, one of the populations of means is different from the other population of mean. Fig. 7 shows the mean of values obtained using the conventional and the developed method. Here X axis denotes the methods used while the corresponding correlation coefficient obtained are plotted along Y axis. It can be noted from the figure that the mean is higher for the developed method and the same is proved using the ANOVA test.

B. Case 2: Analysis of images with five different font styles having 3 different shades

Fig. 7 shows the results obtained for images with five different font styles having 3 different shades (see Fig. 5). The ordering of these font styles is the same as mentioned in Section III.C. The notations Sij along the X-axis denotes images with i (i=1,2,3,4,5) different font styles and j (j=1,2,3) different shades. The notation Ai (i=1,2,3,4,5) are indicative of five different font styles for the character ‘A’. Y axis represents the correlation coefficient values obtained using the conventional (blue line) and the proposed method (red line). It can be inferred from the figure that the proposed method was better than the conventional one.

Single factor ANOVA for case 2

The results shown in Fig. 8 are tested statistically using single factor ANOVA suite with the following hypothesis:

H₀: All the images (with different font styles and shades) return same results.
H₁: All the images (with different font styles and shades) do not return same results.

Table 3 gives the summary of statistical results for case 2. Since the p-value returned by ANOVA test (Table 3) is less than 0.05, we reject the null hypothesis. Hence, the means of the correlation coefficients aren’t equal. Hence, one of the populations of means is different from the other population of mean. Fig. 9 shows the mean of values obtained using the conventional and the developed method. Here, X axis is indicative of the methods used and Y axis corresponds to the correlation coefficient values obtained. It can be noted from the figure that the mean is higher for the developed method and the same is proved using the ANOVA test.
Table 1. Summary of statistical tests

<table>
<thead>
<tr>
<th>Groups</th>
<th>Count</th>
<th>Sum</th>
<th>Average</th>
<th>Variance</th>
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<td>CC_Normal</td>
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Table 2. Summary of ANOVA results

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<tr>
<th>Source of Variation</th>
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<th>df</th>
<th>MS</th>
<th>F</th>
<th>P-value</th>
<th>F crit</th>
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<tbody>
<tr>
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<td>2.45648046</td>
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Table 3. Summary of statistical tests

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Table 4. Summary of ANOVA results

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<tr>
<td>Total</td>
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Fig. 6. Results for images with characters of different font style

Fig. 7. Mean of correlation coefficient values for the conventional and the developed method (Case 1)
V. Conclusion

An intelligent robot was developed which could segregate objects based on the label that the objects contained. A technique was developed for optical character recognition for identifying the characters on the label of the object and segregate accordingly. The OCR method composed of image thresholding, character recognition, image de-noising, image segmentation and correlation coefficient. This method of obtaining the correlation coefficient was later compared against conventional way of assessing the correlation coefficient. It was found that the proposed method of obtaining the correlation coefficient on images of characters was better than the conventional way. The proposed scheme of character recognizing robot can be extended in object recognition and can be deployed in fields like automated library, industries, space missions, etc.

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REFERENCES


Author’s profiles

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