

CFD Investigation of Thermal and Pressurization Performance in LHe Tank

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Abstract

Research on thermal response of liquid helium storage tank is an important part of non-destructive storage technology for liquid helium. However there are few reports on the thermal response of liquid helium storage tanks. Taking the thermal stratification, pressure rise phenomenon and natural convection of liquid helium storage tank as research objects, based on the Lee model, the finite volume method was used for the first time to study the non-steady-state thermal response which simultaneously considering the change of liquid helium and vapor helium properties. Thus the tank pressure, temperature and flow rate distribution at different times were obtained, and the effects of evaporation rate and filling rate on the pressure rise and temperature rise of the storage tank were analyzed. The research shows that with the increase of simulation time, the liquid helium shows thermal stratification. In addition, the pressure is distributed in a stepwise manner which is lower in the upper part, and higher in the lower part, while the pressure distribution in the gas phase space is more uniform; After the liquid helium in the near-wall area is heated, it rises along the wall surface to the free liquid surface under buoyancy lift, and then flows into the main flow area of the liquid helium; As the evaporation rate increases, the temperature rise and pressure rise rate in the gas phase space of the storage tank increase, while the filling rate have less influence on the temperature rise and pressure rise rate. This work provides guidance for non-destructive storage and transportation theory of liquid helium storage tanks.

Index Terms: Liquid helium, Storage tank, Thermal response, Numerical study.

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1. Introduction

With the rapid development of aerospace, military industry and scientific research, the application of helium is becoming more and more important. Because helium resource is rare, cryogenic insulated storage tanks are currently mainly used for storage and transportation of liquid helium. But the boiling point of liquid helium is as low as 4.2K, resulting in heat leakage even if high-vacuum multi-layer insulation structure is adopted in liquid helium storage tanks. The heat leakage will cause liquid helium in the storage tank to evaporate at the phase interface after rising to saturation temperature, resulting in pressure rise in the gas zone of the storage tank, bringing hidden dangers to the safe storage and transportation of liquid helium. However, there are few reports on the thermal response research and the research is not comprehensive enough, which leads to the uncertainty of the thermal response discipline of the liquid helium storage tank. Therefore, it is necessary to research the thermal response phenomenon of liquid helium tanks.

At present, there are three methods for studying the thermal response of liquid helium storage tanks, which are theoretical methods, experimental methods, and numerical simulation methods. The theoretical methods have been in progress since 1950. Initially, liquid hydrogen, liquid, and liquid nitrogen were used as research objects. Later, due to the use of natural gas, the low-temperature storage of LNG was systematically studied. So far, the theory of cryogenic liquid storage is relatively mature. However the models used for liquid hydrogen, liquid nitrogen and LNG such as homogeneous surface evaporation model, saturated homogeneous model may no longer be applicable to liquid helium.

The experimental methods is the main research method for researching of thermal response discipline. However, the experimental method is expensive and there are few related research reports. There are supercritical helium is taken as the research object and the influence of daily evaporation rate and filling rate on the gas pressure of the storage tank is analyzed. The research shows that the gas phase pressure of the storage tank changes in a linear rule[1]. Moreover, there are pressure suppression experiment on a 100L supercritical helium storage tank[2]. In the last century, some scholars used experimental methods to study the temperature distribution and pressure distribution of small liquid helium Dewar. The temperature distribution of liquid helium and gas helium in liquid helium Dewar has been experimentally studied, and drawn the distribution curve of gas-phase temperature[3]. The 200L liquid helium Dewar has also been experimentally studied, so the temperature distribution discipline of helium in the neck tube of the storage tank has been obtained[4]. The 12L spherical liquid helium Dewar has been tested and studied to test the evaporation rate of liquid helium [5]. However, the above experimental research was carried out so early that no profound analysis of the distribution of the flow field, temperature field, and pressure field in the storage tank.

Computational Fluid Dynamics (CFD) is a convenient and low-cost research method[6], which has been widely used in the thermal response research of cryogenic liquids such as LNG, liquid nitrogen and liquid hydrogen. But there are no reports on numerical studies of the thermal response process of liquid helium storage tanks. Although the simulation results cannot completely match the actual thermal response of the liquid helium storage tank, however under the case that theoretical and experimental research cannot obtain comprehensive data on the thermal performance of the liquid helium storage tank, and under the circumstance that there are no article using numerical simulation methods to study the thermal response of liquid helium storage tanks, it is acceptable and meaningful to conduct a pilot research using CFD simulation technology to reveal the discipline of thermal response progress in liquid helium storage tank.

Based on this, considering the changes of physical parameters of liquid helium and gas helium, the thermal stratification, pressure rise discipline and natural convection of liquid helium storage tanks were studied using simulation methods. In this paper, the commercial software Fluent is adopted.

1.1 Physical model

In this paper, the thermal stratification, pressure rise discipline and natural convection in 85m³ horizontal railway liquid helium tanker is taken as the research object. And the structure of the tank is shown in Fig. 1. The inner container is made of 316L stainless steel. The length of the inner container is 14m (excluding the head), which is quite different from the inner diameter of the inner container of 2.8m (diameter). The inner container is axisymmetric about the centerline of the cylinder. Therefore, the three-dimensional model is simplified to a two-dimensional circle with a radius of 1.4m and the center is the origin of coordinates (0,0). In order to analyze the temperature and pressure distribution of the flow field conveniently, an auxiliary analysis line as shown in Fig. 2 is added.

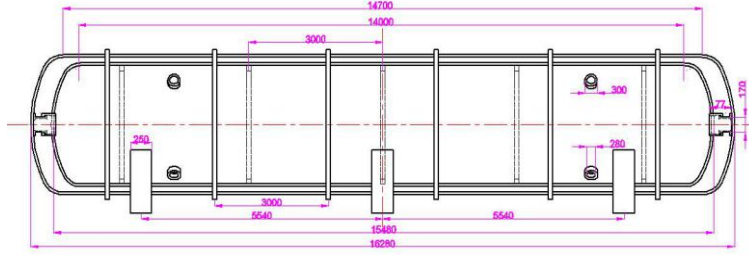


Fig.1 The geometric model of liquid helium tank

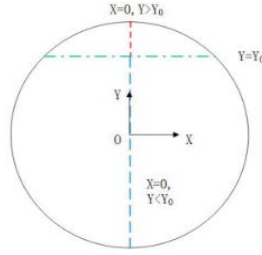


Fig.2 Added auxiliary analysis line

1.2 Mathematical model

$$\begin{aligned}
 \frac{\partial \rho}{\partial t} + \sum_{i=1}^3 \frac{\partial (\rho u_i)}{\partial x_i} &= S_m \\
 \frac{\partial (\rho u_i)}{\partial t} + \frac{\partial (\rho u_i u_j)}{\partial x_j} &= -\frac{\partial p}{\partial x_i} + \frac{\partial}{\partial x_j} \left[\mu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) - \frac{2\mu}{3} \frac{\partial u_i}{\partial x_i} \delta_{ij} \right] + \rho g_i \\
 \frac{\partial (\rho T)}{\partial t} + \text{div}(\rho \vec{u} T) &= \text{div} \left(\frac{\lambda}{c_p} \text{grad} T \right) + S_h
 \end{aligned} \tag{1}$$

1.2.1. Governing equations

The flow, mass transfer and heat transfer process of liquid helium and gas helium in the inner container of the liquid helium storage tank must follow the conservation of mass, the conservation of momentum and the conservation of energy. The governing equation is shown in Eq. (1).

The thermal conductivity of fluid is defined as Eq. (2), energy (E) is treated as mass-averaged variables by Eq.(3).

$$\lambda = \alpha_l \lambda_l + \alpha_v \lambda_v \quad (2)$$

$$E = \frac{\sum_{q=1}^n \alpha_q \rho_q E_q}{\sum_{q=1}^n \alpha_q \rho_q} \quad (3)$$

For each phase, Eq(3) is calculated from its specific heat and temperature. For mass-averaged temperature, E is replaced with T.

1.2.2. Turbulence model

According to the research results of previous scholars on the thermal response law of liquid hydrogen, the natural convection flow pattern along the heated wall is turbulent. Considering that the model of storage tank contains a curved wall surface, therefore, the Realizable k- ε model considering wall surface curvature is selected, and the equation is shown in Eq.(4).

$$\begin{aligned} \frac{\partial(\rho k)}{\partial t} + \frac{\partial(\rho k u_j)}{\partial x_j} &= \frac{\partial}{\partial x_j} \left[\left(\mu + \frac{\mu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_j} \right] + G_k + G_b - \rho \varepsilon - Y_M + S_k \\ \frac{\partial(\rho \varepsilon)}{\partial t} + \frac{\partial(\rho \varepsilon u_j)}{\partial x_j} &= \frac{\partial}{\partial x_j} \left[\left(\mu + \frac{\mu_t}{\sigma_\varepsilon} \right) \frac{\partial \varepsilon}{\partial x_j} \right] + C_{1\varepsilon} \frac{\varepsilon}{k} C_{3\varepsilon} G_b - \rho C_2 \frac{\varepsilon^2}{k + \sqrt{\nu \varepsilon}} \\ &\quad + \rho \varepsilon \sqrt{2 S_{ij} S_{ij}} \max \left[0.43, \frac{k \sqrt{2 S_{ij} S_{ij}}}{5 \varepsilon + k \sqrt{2 S_{ij} S_{ij}}} \right] + S_\varepsilon \end{aligned} \quad (4)$$

1.2.3. Two-phase flow model

Since there is a free liquid surface in the storage tank, the VOF model is selected as the two-phase flow model. The volume ratio equation is shown in Eq. (5)[6].

$$\frac{1}{\rho_q} \left[\frac{\partial}{\partial t} (\alpha_q \rho_q) + \nabla \cdot (\alpha_q \rho_q \vec{v}_q) \right] = \sum_{p=1}^n (\dot{m}_{pq} - \dot{m}_{qp}) \quad \sum_{q=1}^n \alpha_q = 1 \quad (5)$$

Mass or volume-averaged cell properties are used in a control volume containing more than one phases, as appropriate. For instance, viscosity and density, appearing in the transport equations are computed using the following volume-averaged equations.

$$\begin{aligned}\rho &= \alpha_q \rho_q + (1 - \alpha_q) \rho_l \\ \mu &= \alpha_q \mu_q + (1 - \alpha_q) \mu_l\end{aligned}\quad (6)$$

1.3. Phase change model

In this paper, the Lee model is used to describe the evaporation and condensation process of liquid helium [6]. The saturation temperature of liquid helium is selected from the data in reference and the function of saturation temperature with pressure is obtained by polynomial fitting[9]. The Lee model is shown in Eq.(4).

$$\begin{aligned}T_l > T_{sat} \quad S_m &= \dot{m}_v = c \alpha_l \rho_l \left((T_l - T_{sat}) / T_{sat} \right) \\ T_v < T_{sat} \quad S_m &= \dot{m}_l = c \alpha_v \rho_v \left((T_{sat} - T_v) / T_{sat} \right) \\ S_h &= S_m h_{fg}\end{aligned}\quad (7)$$

Table 1 shows the mass transfer intensity factors adopted by different scholars. According to research results of Abdullah Saleem^[6], it has good adaptability to take the mass transfer intensity factor of 0.1. Therefore, in this paper, the mass transfer intensity factor 0.1 is adopted.

Table 1. Application of mass transfer intensity factor

Researchers	De Schepper ^[10]	Wu ^[11]	Yang ^[12]	Goodson ^[13]	Abdullah Saleem ^[6]
Mass transfer intensity factor	0.1	0.1	100	100	0.1 (Good adaptability)

1.4 Boussinesq equation

The flow in the LHe tank is natural convection, through using Boussinesq approximation, a faster convergence can be achieved. This approximation treats density as constant except the buoyancy term in the momentum equation. The essence of this assumption is neglecting the effect of density variation on the flow field, except for the buoyancy term. With this approximation, computational cost, as well as the nonlinearity of the problem, can be reduced significantly. The Boussinesq equation is given by Eq.(8).

$$(\rho - \rho_0) g \approx -\rho_0 \beta (T - T_0) g \quad (8)$$

The Boussinesq approximation is valid for small density changes, $\beta(T - T_0) \ll 1$. In our case, we use Boussinesq approximation for liquid helium density change only.

1.4 Initial and Boundary conditions

The initial velocity of the fluid in the computational domain is 0m/s, the initial temperature of the fluid is 4.2K, and the initial pressure of the gas is 96000Pa.

Due to the low temperature of liquid helium, slight temperature changes in different parts of the inner container of the storage tank have little effect on heat leakage. Therefore, it is assumed that the boundary condition of the wall is the wall boundary with uniform heat flux without slip. In order to quantitatively analyze the influence of evaporation rate on the thermal response process of the storage tank, five conditions of evaporation rate are set for analysis. The lower evaporation rate is 0.484%, which is calculated by Eq(9)[7], and the upper evaporation rate is 0.692%, which is obtained through standards[8]. Heat leakage can be calculated by Eq.(10) the calculated heat leakage is shown in Table 2.

$$q = q_r + q_s + q_i = K \frac{T_h - T_c}{\delta} = (K_r + K_s + K_i) \frac{T_h - T_c}{\delta}$$

$$K_r = \frac{1}{N} \frac{\sigma (T_h + T_c) (T_h^2 + T_c^2)}{\delta_s (\alpha + 2\gamma) / 2n + 1 / \varepsilon_1 + 1 / \varepsilon_1 - 1} \quad (9)$$

$$K_s = \frac{\lambda_p}{2\beta l_0 (n+1) / \delta} P_0$$

$$K_i = aN^2 (T_h + T_c) / 2 + b [(T_h + T_c) (T_h^2 + T_c^2)] / N$$

$$\alpha = \frac{24 \times Q}{\rho V \gamma} \times 100\% \quad (10)$$

Since the filling rate is a major factor affecting the thermal response process of cryogenic storage tanks, it is necessary to study the influence of the filling rate on the thermal response process of storage tanks. The inner container of the liquid helium storage tank needs to reserve 5%-10% of the volume for gas-phase storage. In order to study the influence of initial filling rate on the pressure rise and temperature rise law of the inner container of the storage tank, the liquid filling rate at the initial time is calculated under five working conditions of 90%, 89%, 87.5%, 86%, 85%, and 84%. The liquid level heights at different filling rate can be calculated by Eq(11), the calculated liquid level heights are shown in Table 2.

$$V = V_i + V_f = \frac{1}{2} \pi R^2 L + \int_0^Y 2\sqrt{R^2 - t^2} L dt$$

$$= \frac{1}{2} \pi R^2 L + 2L \left(\frac{1}{2} Y_0 \sqrt{R^2 - Y_0^2} + \frac{1}{2} R^2 \arcsin \frac{Y_0}{R} \right) + \frac{\pi}{18} D^3 + \frac{9}{4} \pi \left(h^2 Y_0 - \frac{1}{3} Y_0^3 \right) \quad (11)$$

Table 2 Heat leakage of the container and level of the liquid helium

Evaporation rate/%	0.692	0.645	0.605	0.565	0.525	0.484
Heat leakage/W	75.002	69.902	65.567	61.232	56.897	52.454
Filling rate/%	0.9	0.89	0.875	0.86	0.85	0.84
Liquid level height/m	0.938	0.903	0.855	0.809	0.779	0.754

2. Numerical implementation

The pressure-based unsteady numerical simulation method in Fluent software is adopted. And Turbulence model, multiphase flow model, and Lee model are set in Fluent software. The whole calculation process meets the equations of mass conservation, momentum conservation, and energy conservation. The continuity equation, momentum equation, and energy equation all adopt the second-order upwind scheme and the pressure-velocity coupling algorithm adopts PISO algorithm. Considering the actual change process of the physical parameters of liquid helium and gas helium, the density and other physical parameters of liquid helium and gas helium take the values in references[9]and[14], so as to add the function of physical parameters on temperature to the material library through polynomial fitting[9,14]. In addition, the surface tension of the liquid surface of the cryogenic storage tank has been studied by using CSF model. Only in microgravity can surface tension affect thermal stratification of cryogenic liquid [15,16]. Therefore, the influence of the surface tension will not be considered. Fig.3 shows flowchart of numerical simulation.

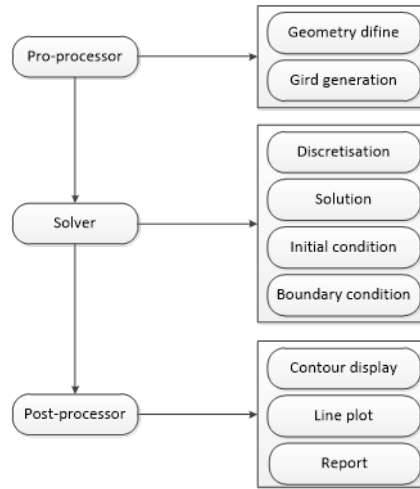


Fig.3 Flowchart of numerical simulation

In this paper, Fluent was used to simulate the thermal response process of liquid helium tank under different evaporation rates and filling rates within 100 minutes.

3. Numerical implementation

3.1 Grid independence study

ICEM is used to divide the computing domain into O-shaped structured grids and the grids near the wall are encrypted. Fig. 4 shows the grid used for CFD simulation.

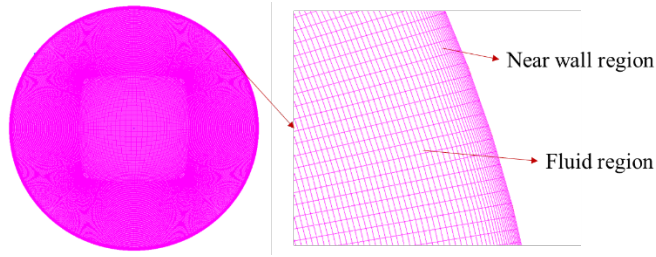


Fig.4 Grid used for CFD simulation

Fig.5 shows the results of grid independence verification. Based on the initial and boundary conditions and coupling algorithm showed above, the CFD model is calculated for 100min under grid 41085, 83205, 151380, 198005 respectively. The average temperature of through line($X=0, Y>Y_0$) in gas zone is obtained by report feature of Fluent, It can be seen that when the number of grids is increased from 151380 to 198005, there is no obvious change in the results. Therefore, the grid 151380 is adopted for calculation in this paper.

3.2 Validation of CFD model

Temperature distribution tested by Bora M.S [4] is used to validate the current CFD model. When the simulation reaches steady state, the average temperature of through line($X=0, Y>Y_0$) in gas zone is taken as the basis for verification, which is obtained by plot feature of Fluent. Fig. 6 displays the comparison of the experiment result and the numerical simulation result.

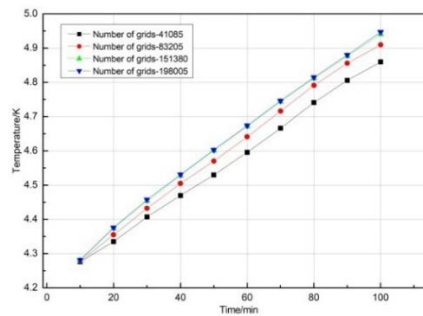


Fig.5 Grid-independent validation

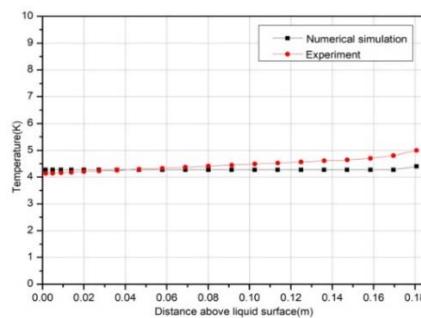


Fig.6 Temperature comparison of the gas field

The comparison shows that the temperature above the free surface is more uniform than the experimental value, and the trend of the two is consistent. Therefore, the model can be used to predict the thermal response of the liquid helium tank.

4. Numerical implementation

4.1 Thermal stratification

Tecplot is used to plot the temperature field with the result calculated by Fluent. Fig. 7 shows the temperature contours of the flow field when the filling rate is 90% and the evaporation rate is 0.484% for 30min, 50min, 70min, and 90min. It can be seen that thermal stratification occurs in the liquid helium storage tank during the thermal response process and the temperature gradient in the gas phase is larger than that in the liquid phase. With the continuous entry of heat, the temperature of gas-phase gradually rises. On both sides of the gas-liquid interface near the wall surface, heat is provided by liquid helium rising along the wall surface on the one hand, and heat flow coming in from the wall surface of the inner container on the other hand. As a result, the temperature on both sides is higher than that in the middle. At the same time, gas helium with slightly higher temperature transfers heat to liquid helium, so the temperature from the wall surface to the middle position on the same isotherm shows a change rule from small to large and then from large to small with a higher temperature area in the middle. In addition, with the increase of simulation time, temperature stratification has gradually formed. For example, the central part of the isotherm has a larger protrusion at 50min and 70min, while the central part of the isotherm is very flat at 100min, which is because heat continuously enters the main flow region of liquid helium through convection and conduction.

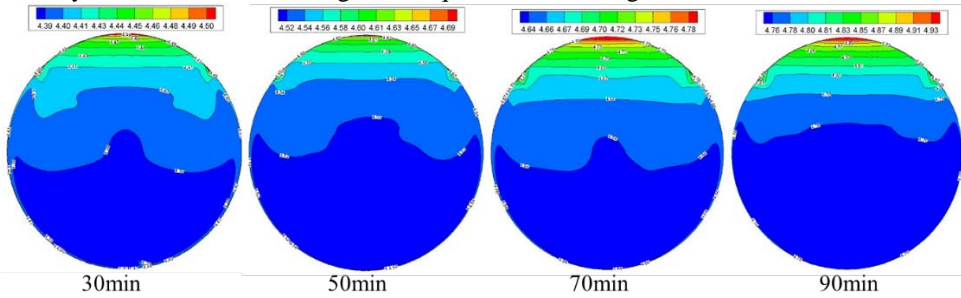


Fig. 7 Temperature distribution of flowfield

The 'plot' feature of Fluent is used to get the temperature of gas phase and free liquid surface. In order to ensure the accuracy of the measurement results, measurements were taken along the pre-defined path line $X=0$, $Y>Y_0$ and $Y=Y_0$. Fig. 8 shows the temperature variation curve of the gas phase of the storage tank and Fig. 9 shows the temperature variation curve of the free liquid surface of the storage tank. It can be seen that the temperature shows a gradual distribution in the vertical direction and the temperature gradient is small. At the same time, the helium gas at the top of the gas phase is slightly higher than the helium gas below it due to the influence of wall heat leakage. On the free liquid surface, the temperature of liquid helium near the wall surface is significantly higher than the temperature of liquid helium inside. The temperature gradient near the wall is large and a thermal boundary layer appears. With the progress of the simulation process, the free surface temperature increases. For example, the free surface temperature is about 4.55K for 50min and 4.8K for 100min.

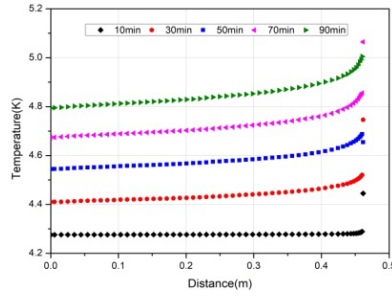


Fig.8 Temperature curve of the gas phase.

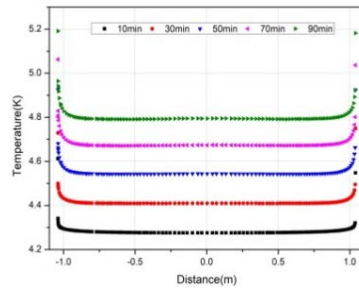


Fig.9 Temperature curve of free surface

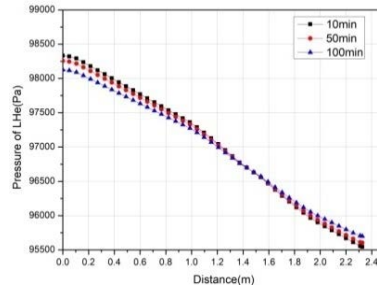


Fig.10 Pressure curve of the liquid phase

4.2 Pressure distribution

Fig. 11 shows the pressure contours of the storage tank when the filling rate is 90%, the evaporation rate is 0.484% for 10min, 50min and 100min. It can be seen that the gas phase pressure has been around 95500Pa. However, in the liquid phase, the pressure distribution in the tank shows a stepped distribution rule with a lower level and a higher level due to static pressure. The pressure on the bottom liquid is the largest, which requires high strength on the tank bottom. Same method as measuring temperature, the pressure in the liquid region was measured. Fig. 10 shows the pressure curve in the liquid helium ($X=0$, $Y<Y_0$). Comparing the curves of Fig. 10, it is found that the pressure in the liquid helium region is approximately linearly distributed. With the increase of simulation time, the pressure at the bottom of the liquid helium decreases slightly, which is because heat gradually enters the liquid helium, warming up the liquid helium slowly, the density gradually decreases. However, the pressure in the top of the liquid helium is slightly increasing, which may be caused by

the liquid helium flowing toward the centre of the liquid surface after rising along with the natural convection on the wall.

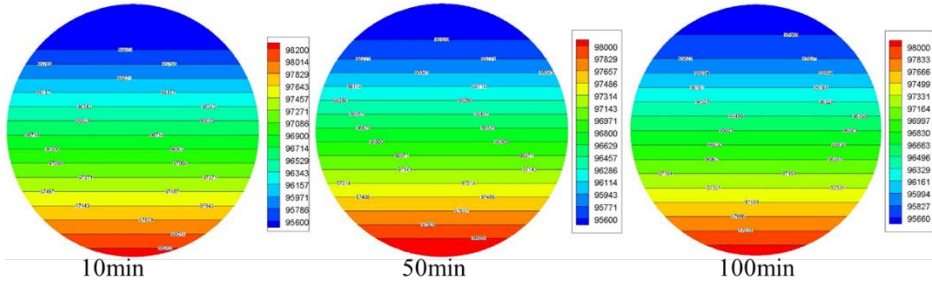


Fig. 11 Pressure distribution of flowfield

4.3 Velocity distribution

Fig.12 shows the velocity contour at 10min, 50min and the velocity vector diagram at 20min, 100min when filling rate is 90%, evaporation rate is 0.484%. Fig. 12 shows the vector diagram of the velocity in the liquid phase, the gas phase and the middle of the liquid phase near the free liquid surface of the tank at 100 min under this condition.

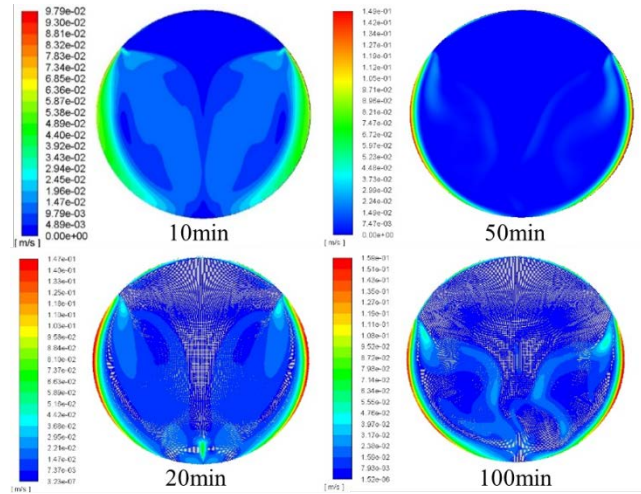


Fig. 12 Velocity diagram and velocity vector diagram of flowfield

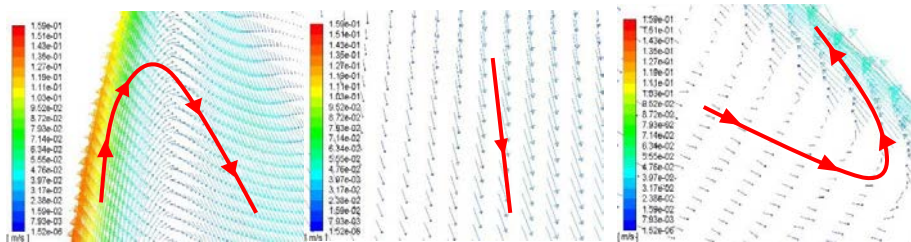


Fig. 13 Velocity vector diagram near the liquid surface (left), gas phase (right) and middle of the liquid phase (middle)

As shown in Fig. 13 (left), it is found that the density of liquid helium at the wall surface decreases after being heated, thus generating natural convection flowing upward along the wall surface by the action of buoyancy force and finally flowing into the liquid helium core area after rising to the free liquid surface. Using the improved Rayleigh number, the Ra^* of natural convection is calculated to be larger than the critical value 1011, so the natural convection flow pattern is turbulent. As the temperature of the flow field rises, the buoyancy force is insufficient to maintain the liquid helium flowing to the free liquid surface. At the same time, with the increase of simulation time, heat continuously enters the liquid phase, making the timing for convective liquid helium to flow out of the wall surface and into the liquid helium core area continuously advance. As shown in Fig. 13 (middle), the part of liquid helium flows to the bottom of the storage tank after flowing into the liquid helium core area to compensate for the energy of the liquid helium. Moreover, helium convection also exists in the gas phase region. As shown in Fig. 13 (right), helium near the wall surface flows upward along the wall surface after being heated, while helium at the upper part of the gas phase flows downward to supplement helium at the bottom of the gas phase. Due to the convection of liquid helium and gas helium, convection circulation occurs in the gas phase and the liquid phase.

In order to study the natural convection process clearly, the 'pathlines' feature of Fluent is used to track the trace of natural convection. Fig. 14 shows the flow path diagram of the flow field for 20min, 40min, 60min, 80min and 100 min, among them, each diagram is composed of two parts, the pathline diagram is in left and the phase diagram is in right. Obviously, there is natural convection cycle in LHe tank.

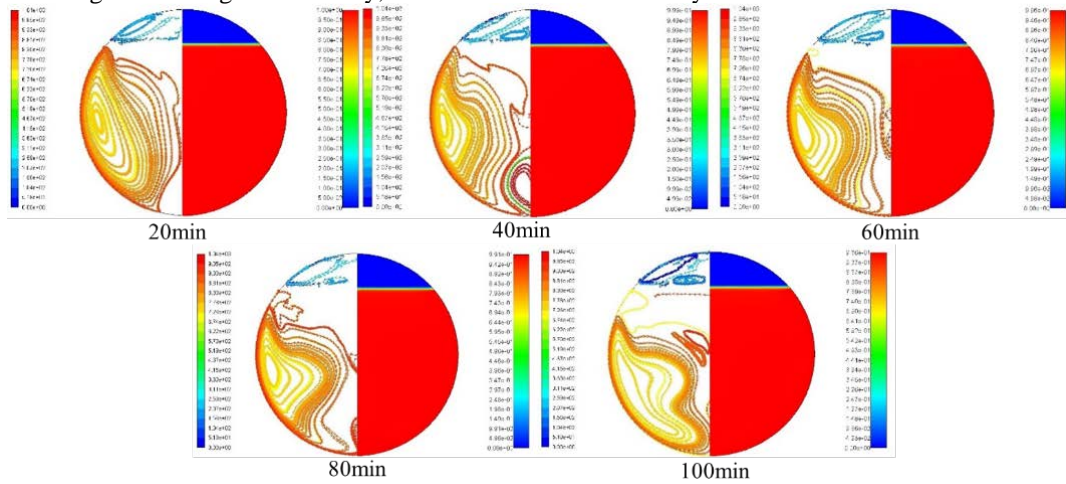


Fig. 14 Pathline diagram of flowfield

At the beginning of the simulation, the convection circulation in the gas and liquid zone is stable. However, with the increase of the simulation time, the circulation in the gas phase and liquid phase is gradually unstable and even secondary circulation occurs in the liquid helium core region and gas helium core region.

4.4 Analysis of temperature and pressure curves

Fig.15 shows the temperature and pressure curves of helium gas at different evaporation rates when the filling rate is 90%. Fig.16 shows the temperature and pressure curves of helium gas at different filling rates when the evaporation rate is 0.484%.

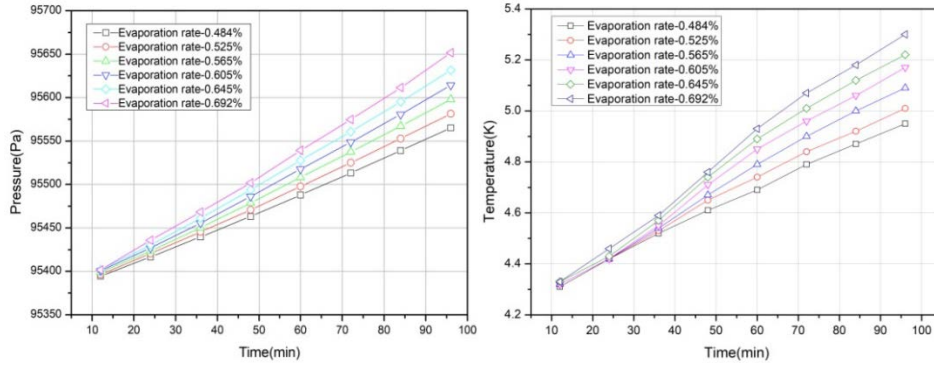


Fig.15 The pressure and temperature curve of GHe at different evaporation rates

Comparing the temperature curve and pressure curve at different evaporation rates, it can be seen that with the increase of simulation time, the pressure and temperature of the gas phase in the storage tank increase approximately linearly. The higher the evaporation rate, the higher the increments in the velocity of pressure and temperature of the gas phase of the storage tank. Therefore, improving the thermal insulation performance of the storage tank is the key to the safe storage and transportation of liquid helium.

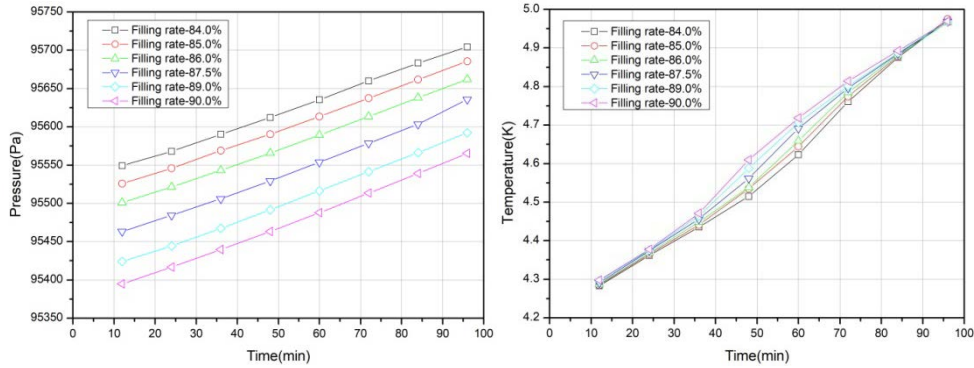


Fig.16 The pressure and temperature curve of GHe at different filling rates

Comparing the pressure curve and temperature curve at different filling rates, it can be seen that the pressure of the gas phase increases linearly. The higher the filling rate, the lower the pressure in the gas phase. But the increments in the velocity of pressure at different filling rate are similar, which may be due to the lower free surface area of liquid helium as the filling rate increases. The temperature of the gas phase increases approximately linearly with the increase of the simulation time. In the process of changing the filling rate from 84% to 90%, the temperature curve of the gas phase in the liquid helium storage tank changes obviously only when the simulation time is about 60min, which indicates that the filling rate has little influence on the temperature law of the gas phase in the storage tank.

5. Conclusions

According to the thermal response process of the 85m³ storage tank of railway tanker filled with liquid helium, the thermal response law of the tank is studied by the numerical method under the premise of

considering the mass transfer and heat transfer between phases. The influence of evaporation rate and filling rate on the pressure and temperature law of the tank is discussed and the following conclusions are obtained:

(1) With the continuous leakage of heat, liquid helium in the tank gradually develops thermal stratification. And the isotherm gradually flattens with the increase of simulation time. Due to the existence of static pressure, the pressure of liquid helium has a stepped distribution with small upper part and large lower part, while the pressure of gas helium has a uniform distribution. With the increase of simulation time, the pressure in the upper part of liquid helium increases slowly, while the pressure in the lower part of liquid helium decreases slowly.

(2) After the tank is heated, the temperature near the wall rises, causing the density to decrease, thus slowly rising to the free liquid surface along the wall by the action of buoyancy force, generating turbulent natural convection. The longer the simulation time, the earlier the rising liquid helium near the wall will flow into the liquid helium.

(3) The higher the evaporation rate of the storage tank, the higher the increments in the velocity of pressure and temperature in the tank. The larger the filling rate, the smaller the initial pressure in the gas phase of the storage tank. Because of the larger the filling rate, the smaller the free liquid surface of liquid helium in the storage tank.

The above research and conclusion have important value to clarify the temperature and pressure rising principle of railway liquid helium storage tanker.

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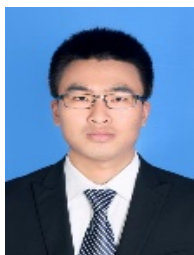
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Appendix

Nomenclature

ρ density, kg/m³;
 ρ_0 reference density at the reference temperature of T_0 ;
 S_h energy source term;
 S_m quality source term;
 E energy;
 p static pressure, Pa;
 g_i gravity force in direction i ;
 λ thermal conductivity of fluid, W/(m·K);
 G_k turbulent flow energy generated by laminar velocity gradient;
 G_b turbulent flow energy generated by buoyancy;
 Y_m the fluctuations caused by diffusion in compressible turbulent flow;
 C_1 constant;
 C_2 constant;
 σ_k Prandtl number of k equation;
 σ_ϵ Prandtl number of ϵ equation;
 Subscripts p and q different phases;
 α_q volume ratio of the q phase fluid;
 $\alpha_q = 0$ no q phase fluid in the unit;
 $0 < \alpha_q < 1$ part of the unit contains the q phase fluid;
 $\alpha_q = 1$ q phase fluid is full in the unit;
 c mass transfer intensity factor with adjustable parameters;
 a phase volume fraction;
 Subscripts l liquid phase;
 Subscripts v vapor phase;
 T_{sat} saturation temperature, K;

T_0	reference temperature, K;
h_{fg}	latent heat of evaporation, 20.4J/kg;
α	evaporation rate, %;
Q	heat leakage,W;
V	tank capacity, m ³ ;
q	heat flux through multiple layers insulation, W/m ² ;
q_r	radiant heat flux, W/m ² ;
q_g	residual gas conduction heat flux, W/m ² ;
q_s	material solid heat conduction heat flux, W/m ² ;
K	comprehensive heat transfer coefficient, W/(m ² • K);
K_r	radiant heat transfer coefficient, W/(m ² • K);
K_g	residual gas heat transfer coefficient, W/(m ² • K);
K_s	material heat conduction heat transfer coefficient, W/(m ² • K);
T_h	hot boundary temperature, K;
T_c	cold boundary temperature, K;
N	layer density of insulation, layer/cm;
δ	thickness of multi-layer insulation, m;
δ_s	thickness of spacer, m;
σ	Stephen-Boltzmann constant, 5.67×10^{-8} W/(m ² • K ⁴);
α	absorption coefficient, m ⁻¹ ;
γ	scattering coefficient, m ⁻¹ ;
n	number of radiation screens;
ε_1	radiation screen emissivity;
ε_2	radiation screen emissivity;
λ_p	thermal conductivity of gas at atmospheric pressure, W/(m • K);
β	Stephen-Boltzmann constant, 5.67×10^{-8} W/(m ² • K ⁴);
l_0	mean free path of gas molecules, cm;
p_0	gas molecular pressure,Pa;
a	material-related coefficient;
b	material-related coefficient;
V_1	volume of cylinder in tank, m ³ ;
V_f	volume of head in tank, m ³ ;
R	radius of cylinder, m;
L	height of cylinder, m;
h	depth of head, m;
Y_0	height of free surface, m;

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