

On the Performance of Priority-Based Virtual Channels Scheduling Algorithm in Packet Telemetry System

TIAN Ye^{1,2}

¹School of Information Science and Engineering, Shenyang Ligong University, Shenyang, China
²State Key Laboratory of Rail Traffic Control and Safety (Beijing Jiaotong University), Beijing, China
Email: tianyereal@126.com

ZHANG Yan-qin*¹ and ZHANG Zi-jing¹

¹School of Information Science and Engineering, Shenyang Ligong University, Shenyang, China
Email*: hnzyq2007@sina.com

Abstract—We Study the performance of priority-based virtual channels scheduling algorithm in packet telemetry system. Probability of occupying physical channel by the virtual channel with the highest priority is considered, on condition that the packet arrival rate contribution is Poisson distribution. Packets losing rate of the virtual channel with the highest priority is also investigated, of which calculating formulas are given. An interesting conclusion is made by theoretical analysis and simulation experiments that when the running time of the scheduling module is long enough, both the probability of being scheduled and packets losing rate of the virtual channel with the highest priority converge on fixed values, which can offer reference to engineering design.

Index Terms—priority; virtual channels; scheduling algorithm; packet telemetry

I. INTRODUCTION

With the development of space science and space technologies, some main worldwide space organizations established Consultive Committee for Space Data Systems (CCSDS) in 1982 to meet the demands of space missions[1]. Since then, CCSDS has designed a group of space communication standards, which are now widely used in more than 250 countries and regions[2-4]. Among these standards, TM Space Data Link protocol is a data communication and transmission protocol, which is mainly used (but not limited) in packet telemetry system to transmit packet telemetry data through the downlink, namely, from space to ground[5-7]. In order to transmit those information better, a two-layer multiplexing mechanism is used in packet telemetry system, which includes packet channel multiplexing mechanism and virtual channel multiplexing mechanism. Packet channel

multiplexing mechanism makes a certain number of data packets share a virtual channel (VC), while virtual channel multiplexing mechanism makes a certain number of virtual channels share a physical channel.

Virtual channels are a group of logic channels formed by dividing the physical channel by different time slots. Each virtual channel transmits the packets information with the same or similar service demands, and the physical channel is shared by all these virtual channels. Thus the physical channel can be used to transmit various upper-layer sources data stream with different types and transmission requirements. The algorithm used in virtual channels mechanism, namely, virtual channels scheduling algorithm, determines the sequence of occupying the physical channel by each virtual channel, which has a great effect on the transmission delay and efficiency. In Packet Telemetry System, the scheduling algorithms often used include mainly first-in-first-out algorithm, maximum remained prior algorithm, polling algorithm, priority-based algorithm. In some complicated systems, dynamic-priority-based algorithm may be used.

In this paper, we study the priority-based virtual channels scheduling algorithm in packet telemetry system. For this algorithm, each VC is assigned a priority number according to its importance and real-time requirements before the system begins to work. The important the VC is, or the higher the real-time required by the VC is, the higher the priority assigned will be. At each scheduling time point, the one with the highest priority among the VCS whose frames buffer does exist frames can be scheduled, and the first frame in its buffer is transmitted through the physical channel (namely, the VC occupies the physical channel). Through theoretical analysis and simulation results, we find an interesting conclusion: when the running time of the scheduling module is long enough, for the VC with the highest priority, both the probability of being scheduled and the packets losing rate converge on fixed values, which can provide reference for engineering design.

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*ZHANG Yan-qin, corresponding author.

II. SYSTEM MODEL

In this paper, we choose the packet telemetry source model, of which the physical channel is divided into 4 virtual channels to transfer all user data through the downlink[8], as illustrated in Fig.1. The 4 virtual channels are shown as follows:

VC1: transmitting general engineering data, with the second higher priority.

VC2: transmitting important express data, with the highest priority.

VC3: transmitting download data, with the lowest priority.

VC4: producing idle frames. At any scheduling time point, if there are no frames in all the other VCs buffers, an idle frame is generated in VC4 buffer and transmitted through the physical channel.

For VC_i, $i=1,2,3$, the packet arriving process is Poisson distribution with the parameter λ_i , and the packet length is a fixed value[9]. Let l_{pi} be the Packet length, and l_{mp} be the MPDU packet zone length of the frame, then each frame contains $N_i = l_{mp} / l_{pi}$ packets, which also means that a frame is generated and sent to the VC_i buffer at the arriving time of the mN_i packet, $m = 1, 2, 3L$.

At each scheduling time point, the scheduling module choose the one with the highest priority among the VCs whose frame buffers are not empty, and transmit the first frame in its buffer through the physical channel. If buffers of VC1, VC2, VC3 are all empty, an idle frame is generated in VC4 buffer and transmitted

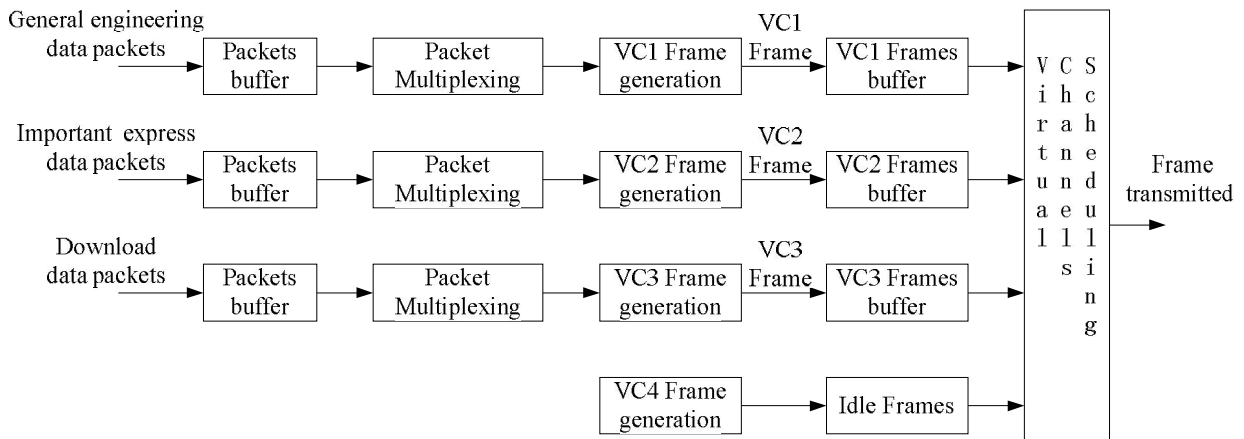


Figure 1. Packet Telemetry Source Model

III. THEORETICAL ANALYSIS

A. the size of packets buffer is infinite

First consider the condition that the size of packets buffer is infinite. At the first scheduling time point, Δt , if there is one frame or more in the VC2 frames buffer, which means the number of packets arriving in the packets buffer during the time interval $[0, \Delta t]$ is larger than or equal to N_2 , VC2 can be scheduled. So we can get the probability of VC2 can be scheduled at the time Δt , $P_{VC2}(\Delta t)$, as

$$P_{VC2}(\Delta t) = P(A_{VC2}(\Delta t) \geq N_2) = \sum_{n=N_2}^{\infty} P(A_{VC2}(\Delta t) = n) \quad (1)$$

where $A_{VC2}(\Delta t)$ means the number of packets arriving in VC2 during the time interval $[0, \Delta t]$. For the packet arriving process which obeys Poisson distribution, the probability of arriving n packets during the time period Δt , $P(A_{VC2}(\Delta t) = n)$, can be calculated as:

$$P(A_{VC2}(\Delta t) = n) = \frac{(\lambda_2 \Delta t)^n e^{-\lambda_2 \Delta t}}{n!} \quad (2)$$

Substituting equation (2) into equation (1), we can get

$$P_{VC2}(\Delta t) = \sum_{n=N_2}^{\infty} \frac{(\lambda_2 \Delta t)^n e^{-\lambda_2 \Delta t}}{n!} \quad (3)$$

Otherwise, if the number of packets arriving in the packets buffer during the time interval $[0, \Delta t]$ is less than N_2 , there will be no frames in VC2 buffer at the time Δt , and VC2 cannot be scheduled. So we can get the probability of VC2 can be scheduled at the time Δt , $P_{VC2}(\Delta t) = 0$, as

$$P_{VC2}(\Delta t) = P(A_{VC2}(\Delta t) < N_2) = \sum_{n=0}^{N_2-1} P(A_{VC2}(\Delta t) = n) \quad (4)$$

Substituting equation (2) into equation (4), we can get

$$P_{VC2}(\Delta t) = \sum_{n=0}^{N_2-1} \frac{(\lambda_2 \Delta t)^n e^{-\lambda_2 \Delta t}}{n!} \quad (5)$$

For the size of packets buffer is infinite, there will be no packets lost. The packets not transmitted at the time Δt will be stored in the packets buffer. Let R_{t1} be the number of packets remained in VC2 packets buffer after the time Δt , $P(R_{t1} = r)$ be the probability of $R_{t1} = r$. If

$r = 0, 1, 2, \dots, N_2 - 1$, r packets remained means that during the time interval $[0, \Delta t]$, there are $N_2 + r$ packets arriving (in this case, VC2 is scheduled, N_2 packets transmitted and r packets remained) or r packets arriving (in this case, VC2 is not scheduled, all of the r packets remained), so we have

$$P(R_{I1} = r) = P(A_{VC2}(\Delta t) = N_2 + r) + P(A_{VC2}(\Delta t) = r) \quad r = 0, 1, \dots, N_2 - 1 \quad (6)$$

Substituting equation (2) into equation (6), we can get

$$P(R_{I1} = r) = \frac{(\lambda_2 \Delta t)^{N_2+r} e^{-\lambda_2 \Delta t}}{(N_2 + r)!} + \frac{(\lambda_2 \Delta t)^r e^{-\lambda_2 \Delta t}}{r!} \quad r = 0, 1, \dots, N_2 - 1 \quad (7)$$

$$P(R_{I1} = r) = \begin{cases} \frac{(\lambda_2 \Delta t)^{N_2+r} e^{-\lambda_2 \Delta t}}{(N_2 + r)!} + \frac{(\lambda_2 \Delta t)^r e^{-\lambda_2 \Delta t}}{r!} & r = 0, 1, \dots, N_2 - 1 \\ \frac{(\lambda_2 \Delta t)^{N_2+r} e^{-\lambda_2 \Delta t}}{(N_2 + r)!} & r = N_2, N_2 + 1, \dots, \infty \end{cases} \quad (9)$$

At the second scheduling time point, $2\Delta t$, if the total number of the packets remained at the time Δt , R_{I1} , and the new packets arriving in the time interval $[\Delta t, 2\Delta t]$, $A_{VC2}(\Delta t)$, is larger than or equal to N_2 , there will be at least one frame in the VC2 frames buffer, and VC2 can be scheduled. Otherwise VC2 cannot be scheduled. Thus we can get the probability of VC2 can be scheduled at the time $2\Delta t$, $P_{IVC2}''(1)$, as

$$P_{IVC2}''(1) = P(R_{I1} + A_{VC2}(\Delta t) \geq N_2) = \sum_{q=N_2}^{\infty} \sum_{r=0}^q P(R_{I1} = r, A_{VC2}(\Delta t) = q - r) \quad (10)$$

For Poisson distribution, R_{I1} and $A_{VC2}(\Delta t)$ are independent of each other, so we have

$$P_{IVC2}''(1) = \sum_{q=N_2}^{\infty} \sum_{r=0}^q P(R_{I1} = r, A_{VC2}(\Delta t) = q - r) = \sum_{q=N_2}^{\infty} \sum_{r=0}^q P(R_{I1} = r) \cdot P(A_{VC2}(\Delta t) = q - r) \quad (11)$$

where the values of $P(A_{VC2}(\Delta t) = q - r)$ and $P(R_{I1} = r)$ can be calculated by using equation (2) and equation (9), respectively.

$$P(R_{I2} = r) = P(R_{I1} + A_{VC2}(\Delta t) = N_2 + r) + P(R_{I1} + A_{VC2}(\Delta t) = r) = \sum_{q=0}^{N_2+r} P(R_{I1} = q, A_{VC2}(\Delta t) = N_2 + r - q) + \sum_{q=0}^r P(R_{I1} = q, A_{VC2}(\Delta t) = r - q) = \sum_{q=0}^{N_2+r} P(R_{I1} = q) \cdot P(A_{VC2}(\Delta t) = N_2 + r - q) + \sum_{q=0}^r P(R_{I1} = q) \cdot P(A_{VC2}(\Delta t) = r - q) \quad (13)$$

$$r = 0, 1, \dots, N_2 - 1$$

If $r = N_2, N_2 + 1, \dots, \infty$, r packets remained means that during the time interval $[0, \Delta t]$, there are $N_2 + r$ packets arriving (VC2 is scheduled, N_2 packets transmitted and r packets remained), so we have

$$P(R_{I1} = r) = P(A_{VC2}(\Delta t) = N_2 + r) = \frac{(\lambda_2 \Delta t)^{N_2+r} e^{-\lambda_2 \Delta t}}{(N_2 + r)!} \quad (8)$$

$$r = N_2, N_2 + 1, \dots, \infty$$

Combing equation (7) and (8), $P(R_{I1} = r)$ can be expressed as

The probability of VC2 cannot be scheduled at the time $2\Delta t$, $P_{IVC2}''(0)$, can be calculated as

$$P_{IVC2}''(0) = \sum_{q=0}^{N_2-1} \sum_{r=0}^q P(R_{I1} = r, A_{VC2}(\Delta t) = q - r) = \sum_{q=0}^{N_2-1} \sum_{r=0}^q P(R_{I1} = r) \cdot P(A_{VC2}(\Delta t) = q - r) \quad (12)$$

Let R_{I2} be the number of packets remained in VC2 packets buffer after the time $2\Delta t$, $P(R_{I2} = r)$ be the probability of $R_{I2} = r$. If $r = 0, 1, 2, \dots, N_2 - 1$, r packets remained means that the total number of the packets remained at the time Δt , R_{I1} , and the new packets arriving in the time interval $[\Delta t, 2\Delta t]$, $A_{VC2}(\Delta t)$, is $N_2 + r$ (in this case, VC2 is scheduled at the time $2\Delta t$, N_2 packets transmitted and r packets remained) or r (in this case, VC2 is not scheduled at the time $2\Delta t$, all of the r packets remained), so we have

If $r = N_2, N_2 + 1, \dots, \infty$, r packets remained means that the total number of the packets remained at the time Δt , R_{t_1} , and the new packets arriving in the time interval $[\Delta t, 2\Delta t]$, $A_{VC2}(\Delta t)$, is $N_2 + r$ (VC2 is scheduled at the time $2\Delta t$, N_2 packets transmitted and r packets remained), so we have

$$\begin{aligned} P(R_{t_2} = r) &= P(R_{t_1} + A_{VC2}(\Delta t) = N_2 + r) \\ &= \sum_{q=0}^{N_2+r} P(R_{t_1} = q, A_{VC2}(\Delta t) = N_2 + r - q) \quad (14) \\ &= \sum_{q=0}^{N_2+r} P(R_{t_1} = q) \cdot P(A_{VC2}(\Delta t) = N_2 + r - q) \\ & \quad r = N_2, N_2 + 1, \dots, \infty \end{aligned}$$

Combining equation (13) and (14), $P(R_{t_2} = r)$ can be expressed as

$$P(R_{t_2} = r) = \begin{cases} \sum_{q=0}^{N_2+r} P(R_{t_1} = q) \cdot P(A_{VC2}(\Delta t) = N_2 + r - q) + \sum_{q=0}^r P(R_{t_1} = q) \cdot P(A_{VC2}(\Delta t) = r - q), & r = 0, 1, \dots, N_2 - 1 \\ \sum_{q=0}^{N_2+r} P(R_{t_1} = q) \cdot P(A_{VC2}(\Delta t) = N_2 + r - q), & r = N_2, N_2 + 1, \dots, \infty \end{cases} \quad (15)$$

Similarly, at the k th scheduling time point, $k\Delta t$, if the total number of the remained packets at the time $(k-1)\Delta t$, R_{k-1} , and the number of packets arriving during the time period $[(k-1)\Delta t, k\Delta t]$, $A_{VC2}(\Delta t)$, is larger than or equal to N_2 , there will be at least one frame in the VC2 frames buffer. Thus VC2 can be scheduled. Otherwise VC2 cannot be scheduled. So at the time $k\Delta t$, the probability of VC2 can be scheduled, $P_{VC2}^{(k)}(1)$, and the probability of VC2 cannot be scheduled, $P_{VC2}^{(k)}(0)$, can be expressed as

$$\begin{aligned} P_{VC2}^{(k)}(1) &= P(R_{k-1} + A_{VC2}(\Delta t) \geq N_2) \\ &= \sum_{q=N_2}^{\infty} \sum_{r=0}^q P(R_{k-1} = r, A_{VC2}(\Delta t) = q - r) \quad (16) \\ &= \sum_{q=N_2}^{\infty} \sum_{r=0}^q P(R_{k-1} = r) \cdot P(A_{VC2}(\Delta t) = q - r) \end{aligned}$$

$$P(R_{t_k} = r) = \begin{cases} \sum_{q=0}^{N_2+r} P(R_{t_{k-1}} = q) \cdot P(A_{VC2}(\Delta t) = N_2 + r - q) + \sum_{q=0}^r P(R_{t_{k-1}} = q) \cdot P(A_{VC2}(\Delta t) = r - q), & r = 0, 1, \dots, N_2 - 1 \\ \sum_{q=0}^{N_2+r} P(R_{t_{k-1}} = q) \cdot P(A_{VC2}(\Delta t) = N_2 + r - q), & r = N_2, N_2 + 1, \dots, \infty \end{cases} \quad (18)$$

$$k = 3, 4, \dots, \infty$$

B. the size of packets buffer is finite

In practical application, the size of packets buffer is often finite. In this case, the performance of the scheduling algorithm is different from that of the analysis above.

At the first scheduling time point, Δt , if the number of packets arriving in VC2 packets buffer is larger than N_2 , then there will be at least one frame in VC2 frames buffer, which means VC2 can occupy physical channel. So we

$$\begin{aligned} P_{VC2}^{(k)}(0) &= P(R_{k-1} + A_{VC2}(\Delta t) < N_2) \\ &= \sum_{q=0}^{N_2-1} \sum_{r=0}^q P(R_{k-1} = r, A_{VC2}(\Delta t) = q - r) \quad (17) \\ &= \sum_{q=0}^{N_2-1} \sum_{r=0}^q P(R_{k-1} = r) \cdot P(A_{VC2}(\Delta t) = q - r) \end{aligned}$$

$$k = 3, 4, \dots, \infty$$

Let R_{t_k} be the number of packets remained in VC2 packets buffer after the time $k\Delta t$, $P(R_{t_k} = r)$ be the probability of $R_{t_k} = r$, using the method of getting equation (15), we can get

have the probability of VC2 occupying physical channel at the time Δt , $P_{VC2}^{(1)}(1)$, as

$$P_{VC2}^{(1)}(1) = P(A_{VC2}(\Delta t) \geq N_2) = \sum_{n=N_2}^{\infty} \frac{(\lambda_2 \Delta t)^n e^{-\lambda_2 \Delta t}}{n!} \quad (19)$$

where $A_{VC2}(\Delta t)$ means the number of packets arriving in VC2 during the time interval $[0, \Delta t]$, whose value can be calculated by equation (2).

Otherwise, there will be no frames in VC2 frames buffer, which means VC2 can not occupy physical

channel. So we have the probability of VC2 not occupying physical channel at the time Δt , $P_{VC2}(0)$, as

$$P_{VC2}(0) = P(A_{VC2}(\Delta t) < N_2) = \sum_{n=0}^{N_2-1} \frac{(\lambda_2 \Delta t)^n e^{-\lambda_2 \Delta t}}{n!} \quad (20)$$

Let M be the capacity of the VC2 packets buffer, probability of losing d packets of VC2 at the time Δt , $P_{IVC2}(d)$, can be expressed as:

$$P_{IVC2}(d) = \begin{cases} \sum_{n=0}^M \frac{e^{-\lambda_2 \Delta t} (\lambda_2 \Delta t)^n}{n!} & d = 0 \\ \frac{e^{-\lambda_2 \Delta t} (\lambda_2 \Delta t)^{M+d}}{(M+d)!} & d = 1, 2, \dots, \infty \end{cases} \quad (21)$$

After the first scheduling time point, probability of r packets remained in VC2 packets buffer, $P_{R_{VC2}}(r)$, is

$$P_{R_{VC2}}(r) = \begin{cases} \frac{(\lambda_2 \Delta t)^{N_2+r} e^{-\lambda_2 \Delta t}}{(N_2+r)!} + \frac{(\lambda_2 \Delta t)^r e^{-\lambda_2 \Delta t}}{r!} & r = 0, 1, \dots, M - N_2 - 1 \\ \sum_{i=M}^{\infty} \frac{(\lambda_2 \Delta t)^i e^{-\lambda_2 \Delta t}}{i!} + \frac{(\lambda_2 \Delta t)^{M-N_2} e^{-\lambda_2 \Delta t}}{(M-N_2)!} & r = M - N_2 \\ \frac{(\lambda_2 \Delta t)^r e^{-\lambda_2 \Delta t}}{r!} & M - N_2 < r < N_2 \\ 0 & \text{others} \end{cases} \quad (22)$$

if $N_2 < M < 2N_2$;

$$P_{R_{VC2}}(r) = \begin{cases} \frac{(\lambda_2 \Delta t)^{N_2+r} e^{-\lambda_2 \Delta t}}{(N_2+r)!} + \frac{(\lambda_2 \Delta t)^r e^{-\lambda_2 \Delta t}}{r!} & r = 0, 1, \dots, N_2 - 1 \\ \frac{(\lambda_2 \Delta t)^{N_2+r} e^{-\lambda_2 \Delta t}}{(N_2+r)!} & N_2 - 1 < r < M - N_2 \\ \sum_{i=M}^{\infty} \frac{(\lambda_2 \Delta t)^i e^{-\lambda_2 \Delta t}}{i!} & r = M - N_2 \\ 0 & \text{others} \end{cases} \quad (23)$$

if $M \geq 2N_2$

Similarly, at the k th scheduling time point, $k\Delta t$, $k = 2, 3, \dots$, when the total number of the packets remained after the time $(k-1)\Delta t$, $R_{VC2}((k-1)\Delta t)$, and the packets arriving during the time interval $[(k-1)\Delta t, k\Delta t]$, $A_{VC2}((k-1)\Delta t, k\Delta t)$, is larger than or equal to N_2 , there will be at least one frame in VC2 frames buffer. In this case, VC2 can be scheduled and the first frame in its buffer is transmitted through the physical channel, otherwise it cannot be scheduled. Thus we can get

$$P_{VC2}^{(k)}(1) = \mathcal{P}([R_{VC2}((k-1)\Delta t) + A_{VC2}((k-1)\Delta t, k\Delta t)] \geq N_2) \\ = \sum_{q=N_2}^{\infty} \sum_{i=0}^q P_{R_{VC2}}^{(k-1)}(i) P(A(\Delta t) = q-i) \quad (24)$$

$$P_{VC2}^{(k)}(0) = \mathcal{P}([R_{VC2}((k-1)\Delta t) + A_{VC2}((k-1)\Delta t, k\Delta t)] < N_2) \\ = \sum_{q=0}^{N_2-1} \sum_{i=0}^q P_{R_{VC2}}^{(k-1)}(i) P(A_{VC2}(\Delta t) = q-i) \quad (25)$$

where $P_{VC2}^{(k)}(1)$ and $P_{VC2}^{(k)}(0)$ are the probability of VC2 can be scheduled and cannot be scheduled at the time $k\Delta t$, respectively.

Probability of losing d packets of VC2 at the time $k\Delta t$ can be expressed as:

$$P_{vc2}^{(k)}(d) = \begin{cases} \sum_{q=0}^M \sum_{i=0}^q P_{R_{vc2}}^{(k-1)}(i) P(A_{vc2}(\Delta t) = q-i) & d=0 \\ \sum_{q=0}^{M+d} P_{R_{vc2}}^{(k-1)}(q) P(A_{vc2}(\Delta t) = M+d-q) & d=1,2,\mathbf{L},\infty \end{cases} \quad (26)$$

After the k th scheduling time point, probability of r packets remained in VC2 packets buffer is

$$P_{R_{vc2}}^{(k)}(r) = \begin{cases} \sum_{q=0}^{N_2+r} P_{R_{vc2}}^{(k-1)}(q) P(A_{vc2}(\Delta t) = N_2+r-q) + \sum_{q=0}^r P_{R_{vc2}}^{(k-1)}(q) P(A_{vc2}(\Delta t) = r-q) & r=0,1,\mathbf{L},M-N_2-1 \\ \sum_{i=M}^{\infty} \left(\sum_{q=0}^i P_{R_{vc2}}^{(k-1)}(q) P(A_{vc2}(\Delta t) = i-q) \right) + \sum_{q=0}^{M-N_2} P_{R_{vc2}}^{(k-1)}(q) P(A_{vc2}(\Delta t) = M-N_2-q) & r=M-N_2 \\ \sum_{q=0}^r P_{R_{vc2}}^{(k-1)}(q) P(A_{vc2}(\Delta t) = r-q) & M-N_2 < r < N_2 \\ 0 & \text{others} \end{cases} \quad (27)$$

if $N_2 < M < 2N_2$;

$$P_{R_{vc2}}^{(k)}(r) = \begin{cases} \sum_{q=0}^{N_2+r} P_{R_{vc2}}^{(k-1)}(q) P(A_{vc2}(\Delta t) = N_2+r-q) + \sum_{q=0}^r P_{R_{vc2}}^{(k-1)}(q) P(A_{vc2}(\Delta t) = r-q) & r=0,1,\mathbf{L},N_2-1 \\ \sum_{q=0}^{N_2+r} P_{R_{vc2}}^{(k-1)}(q) P(A_{vc2}(\Delta t) = N_2+r-q) & N_2-1 < r < M-N_2 \\ \sum_{i=M}^{\infty} \left(\sum_{q=0}^i P_{R_{vc2}}^{(k-1)}(q) P(A_{vc2}(\Delta t) = i-q) \right) & r=M-N_2 \\ 0 & \text{others} \end{cases} \quad (28)$$

if $M \geq 2N_2$

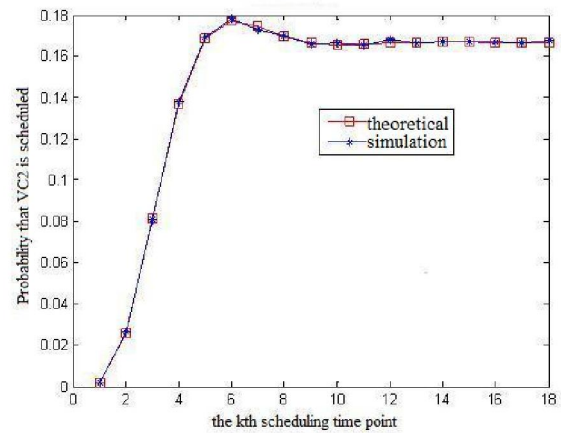
$k=2,3\mathbf{L},\infty$

IV. SIMULATION RESULTS

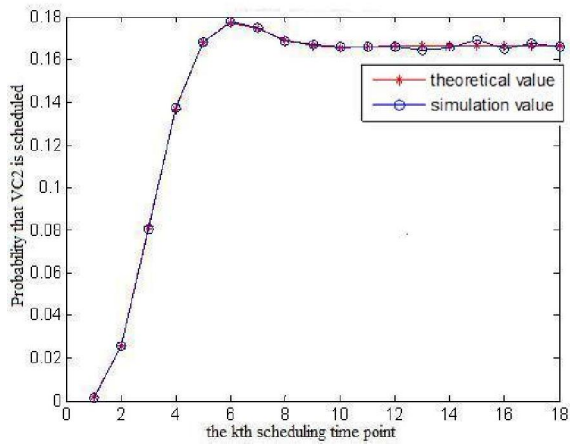
Simulation parameters are set as follows:

- (1) Source data rate of VC1, VC2 and VC3 are taken 10,10, 35 Mbps, respectively;
- (2) The MPDU packet zone length of frame, l_{mp} , is 10000bits;
- (3) The packet length of VC1, VC2 and VC3 are 1000, 2000, 500bits, respectively;
- (4) The average packet arrival rate of VC1, VC2 and VC3 are 10000, 5000, 70000/s, respectively;
- (5) The total simulation time T is 0.8s.

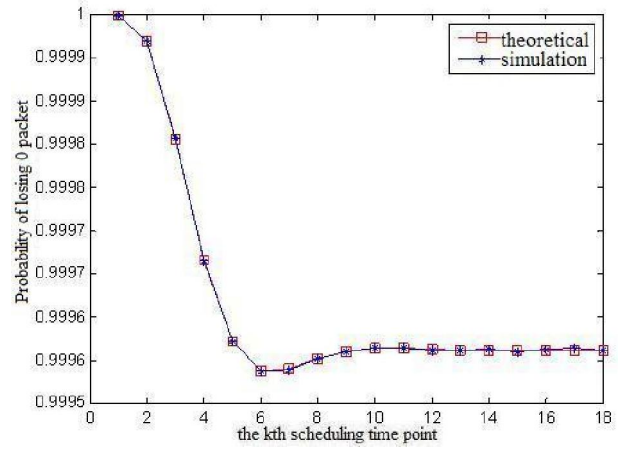
Fig.2 illustrates the probability that VC2 is scheduled at different scheduling time points.



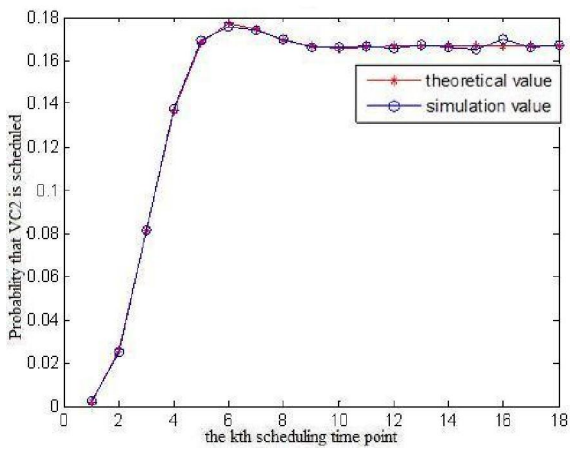
(a) M is infinite



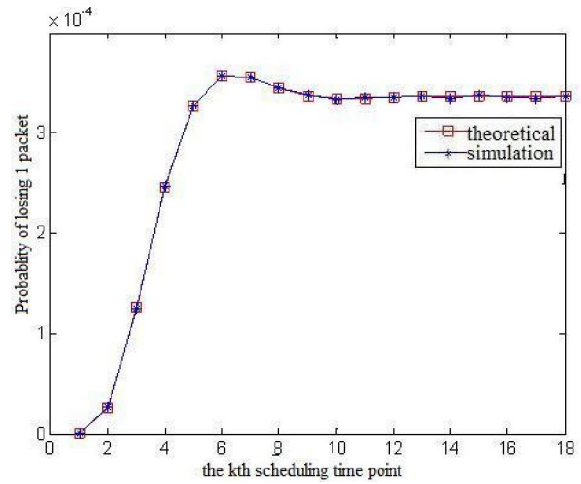
(b) $N_2 < M < 2N_2 (M = 8, N_2 = 5)$



(a) Probability of losing 0 packet



(c) $M \geq 2N_2 (M = 15, N_2 = 5)$

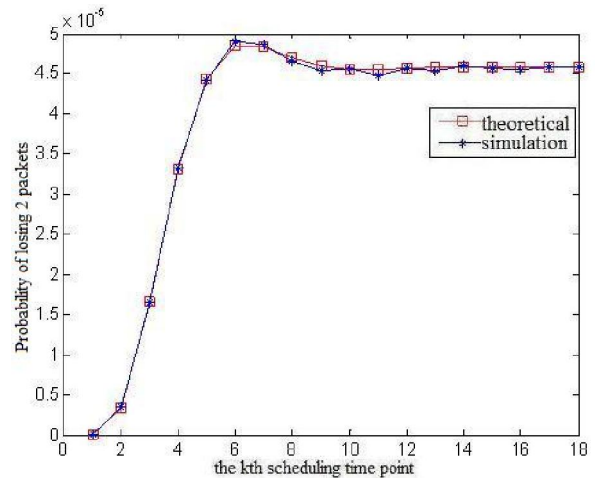


(b) Probability of losing 1 packet

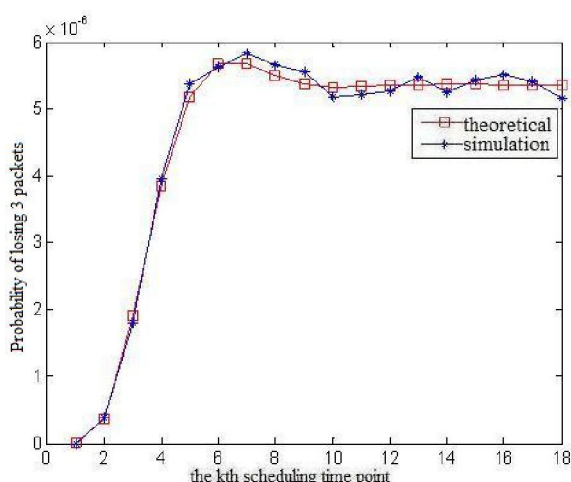
Figure 2. Probability that VC2 is scheduled at different scheduling time points

From the simulation results we can see that with the increasing of the running time of the scheduling module, the probability that VC2 can be scheduled converges on a fixed value, and the simulation curve almost completely coincides with the theoretical curve, which proves the correctness of the analysis in section III.

Fig.3 illustrates the curve of the theoretical value and simulation value of the packets losing rate of VC2 at different scheduling time points when the packet buffer capacity is $M (M = 8)$, which proves the correctness of equation(26). In practical application, one can design the value of M according to the desired packets losing rate.



(c) Probability of losing 2 packets



(d) Probability of losing 3 packets

Figure.3 Packets losing rate of VC2 at different scheduling time point

V. CONCLUSION

We study the scheduling algorithm based on priority in packet telemetry system. Through severe reasoning and simulation experiment, we find that when the running time of the scheduling module is long enough, the probability that the VC with the highest priority can be scheduled converges on a fixed value. We also propose the method to calculate packets losing rating of the VC with the highest priority, which can offer reference to engineering design.

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TIAN Ye, born in 1977, received Doctor's degree of Communication and Information Systems in 2007, Beijing Jiaotong University, China. Major field includes satellite communications and mobile communications.

He works as a researcher in Shenyang Ligong University, China, form 2007. His current research interests are the key technologies of Advanced Orbiting Systems and signal processing technologies in high speed mobile communication systems.

ZHANG Yan-qin, born in 1984, post graduate.

ZHANG Zi-jing, born in 1984, post graduate.